

Anthropomorphic Phantoms in Geant4

Geant4 Training Course in Medicine 2023
Hokkaido University

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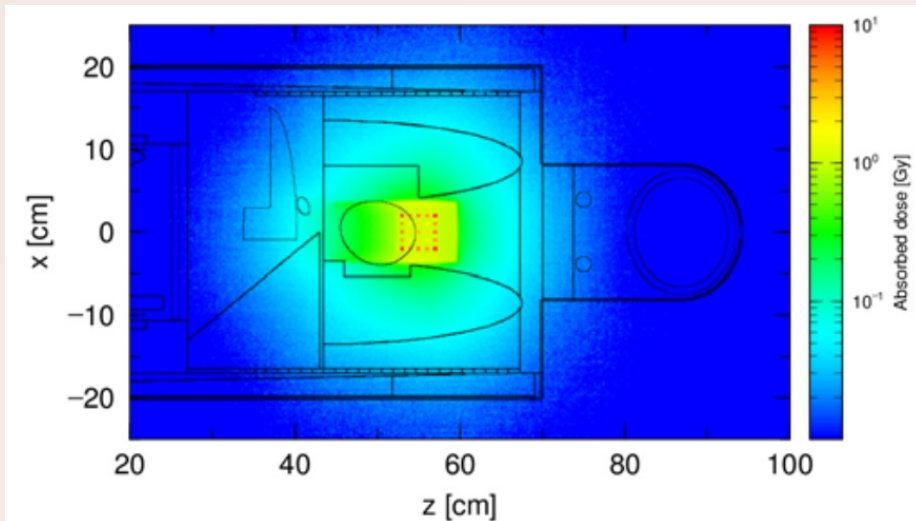
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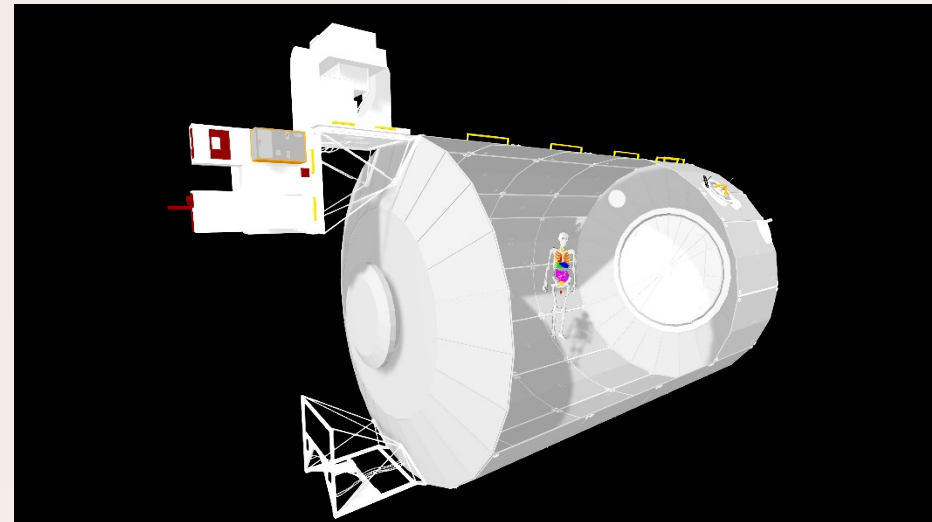


Why Human Phantoms?

- Many different applications of anthropomorphic phantom models:
 - Reference individuals are required for radiological protection and monitoring
 - Required for internal dosimetry (e.g. radionuclides in nuclear medicine and targeted therapies)
 - General radiation transport calculations



MIRD phantoms used for high dose rate superficial brachytherapy²



Space radiation protection in the ISS

¹ ICRP, 1975. *ICRP Publication 23*

² Ohta et. al., 2017. *Energy Procedia* **131**

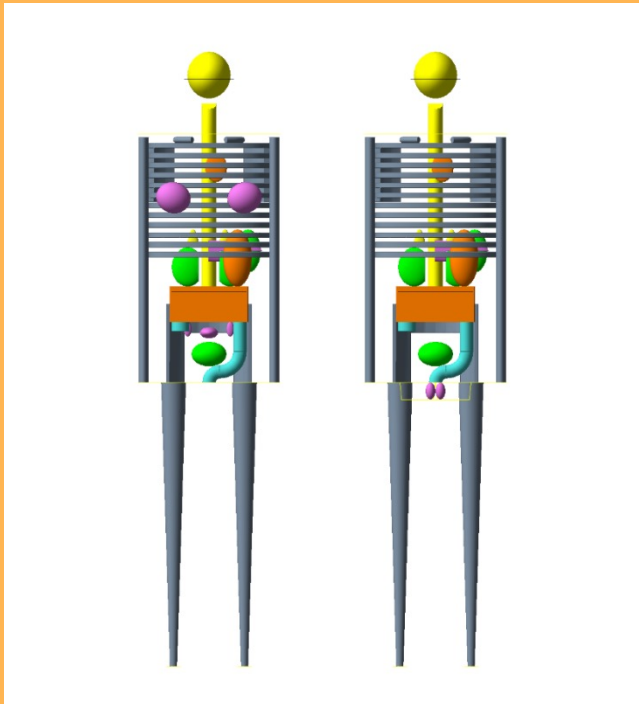
Why Human Phantoms?

- Whilst there are several publically available phantoms, they all have limitations:
 - Variability in structure due to age, race and other factors
 - Other factors contribute to the risk assessment:
 - differing iodine metabolism
 - water balance depends on environmental factors

Types of Human Phantoms in Geant4

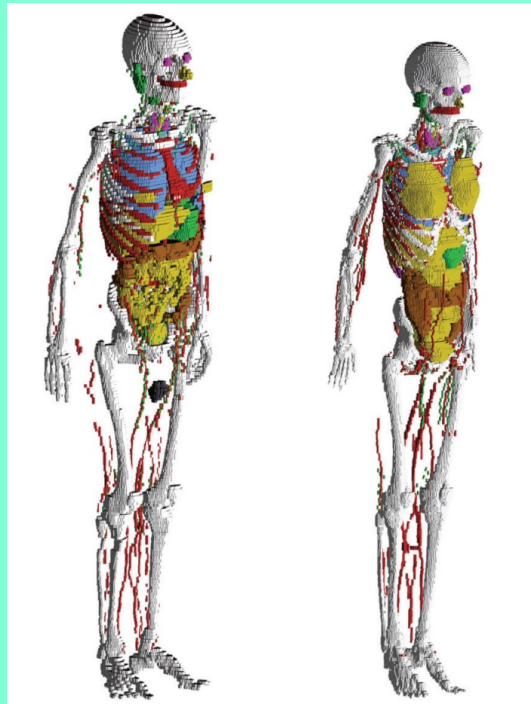
- There are several different phantom of varying complexity included in Geant4:

MIRD/ORNL



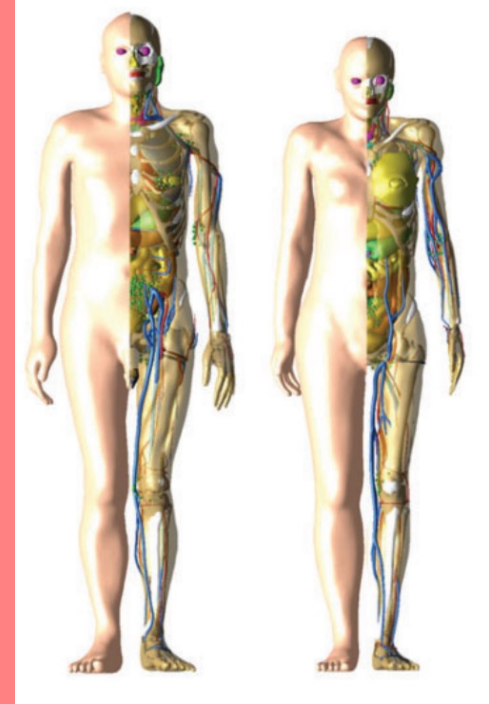
advanced/human_phantom

ICRP110



advanced/ICRP110_HumanPhantoms

ICRP145



advanced/ICRP145_HumanPhantoms

- All available as [advanced examples](#)

MIRD Phantoms

- The Medical Internal Radiation Dose (MIRD) committee developed the adult MIRD phantom ^{3, 4}
 - Extended to children of different ages
 - Extended to male, female and pregnant female models
- Male and female phantoms are included in the *human_phantoms* advanced example

³ ICRP, 1975. *ICRP Publication 23*

⁴ Snyder et. al., 1969. *Journal of Nuclear Medicine Supplemental 3*

MIRD Phantoms

- The MIRD phantom contains *hard-coded* volumes using CSG solids

Example: Liver

G4MirdLiver.cc

```
G4VPhysicalVolume* G4MIRDLiver::Construct(const G4String& volumeName,
G4VPhysicalVolume* mother, const G4String& colourName, G4bool wireFrame, G4bool)
{
    ...

    G4EllipticalTube* firstLiver = new G4EllipticalTube("FirstLiver", dx, dy, dz);

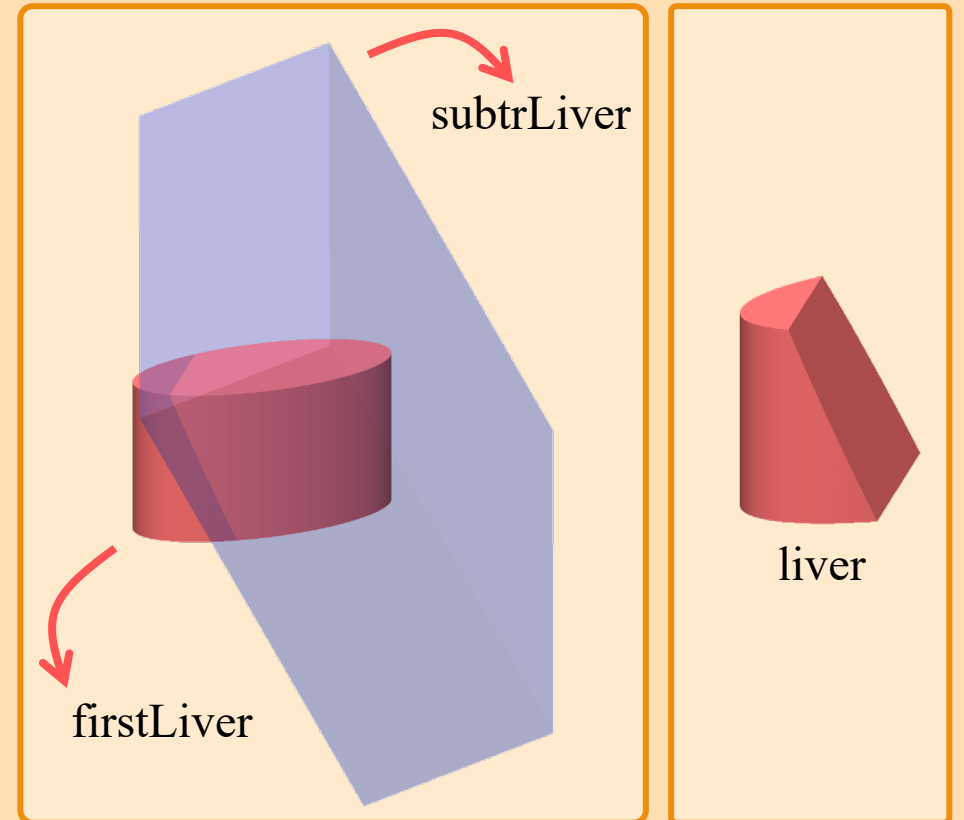
    G4Box* subtrLiver = new G4Box("SubtrLiver", xx/2., yy/2., zz/2.);

    G4RotationMatrix* rm_relative = new G4RotationMatrix();
    rm_relative -> rotateY(32.* degree);
    rm_relative -> rotateZ(40.9* degree);

    G4SubtractionSolid* liver = new G4SubtractionSolid("Liver",
        firstLiver, subtrLiver,
        rm_relative,
        G4ThreeVector(10.0*cm, 0.0*cm, 0.0 *cm));

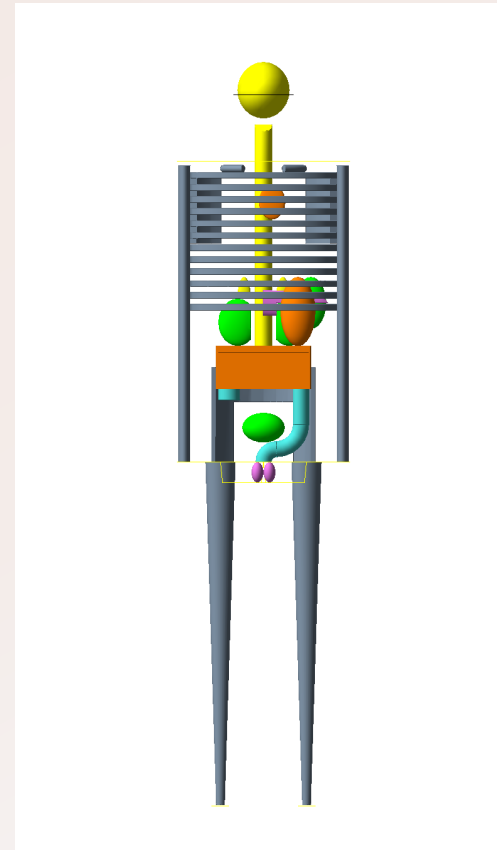
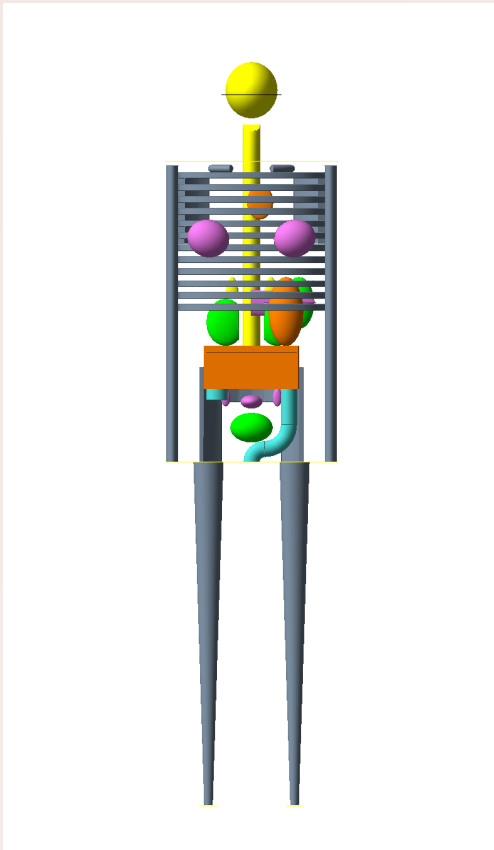
    ...

    return physLiver;
}
```



MIRD Phantoms

- Geometry Description Markup Language (GDML) ⁵ files are available for reference, but are not used for the simulation



⁵ cern.ch/gdml

ORNL Phantoms

- The Oak Ridge National Laboratory (ORNL) developed early anatomical phantoms from Boolean operations on geometric shapes ⁶
- Whilst phantoms of newborns through to an adult is available, the male and female adult phantoms are only available in Geant4
- The organs of the ORNL phantoms are imported directly from GDML files

Example macro file

```
/phantom/setPhantomModel ORNLFemale # Can also be ORNLMale, MIRD, MIRDHead, ORNLHead  
  
/phantom/setPhantomSex Female # Can also be Male  
  
/phantom/buildNewPhantom  
  
/run/initialize
```

⁶ Cristy and Eckerman, 1987. *ORNL/TM-8381/VI*

MIRD/ORNL: Advanced Analysis

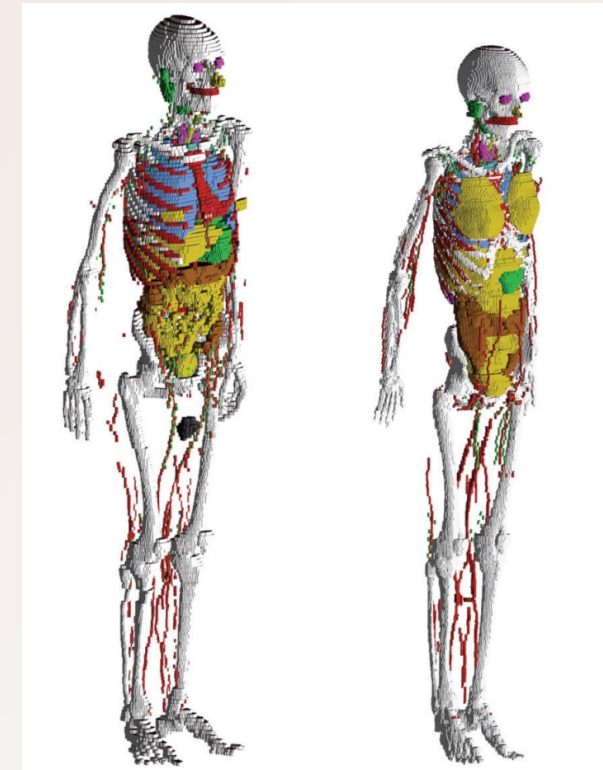
- By default, the simulation outputs the energy deposited in each organ
- To perform custom analysis, the organ volume at a given step point can be obtained from the *G4LogicalVolume*:

```
void SteppingAction::UserSteppingAction(const G4Step* step)
{
    G4String bodyPartName = step->GetPreStepPoint()->GetTouchable()->GetVolume()->GetLogicalVolume()->GetName();

    if (bodyPartName == "Liver")
    {
        // Do something...
    }
}
```

ICRP110 Voxelised Phantoms

- ICRP Report 110⁷ outlined a *voxel* phantom based on medical imaging
- Most organs relevant for radiological assessment are described
- The height of the voxels (z) were scaled to a reference height, whilst the width (x, y) were scaled to the skeletal mass
- Male and female phantoms included:



⁷ ICRP, 2009. *Annals of the ICRP* ICRP 39(2)

ICRP110 Voxelised Phantoms

Property	Male	Female
Height (m)	1.76	1.63
Mass (kg)	73.0	60.0
Number of tissue voxels	1,946,375	3,886,020
Slice thickness (voxel height, mm)	8.0	4.84
Voxel in-plane resolution (mm)	2.137	1.775
Voxel volume (mm ³)	36.54	15.25
Number of columns	254	299
Number of rows	127	137
Number of slices	220 (+2)*	346 (+2)*

⁷ ICRP, 2009. *Annals of the ICRP* ICRP 39(2)

ICRP110 Phantom Implementation

- Implemented in a Geant4 advanced example *ICRP110_HumanPhantoms*⁸
- Created using a parameterised geometry (*G4VNestedParameterisation*)

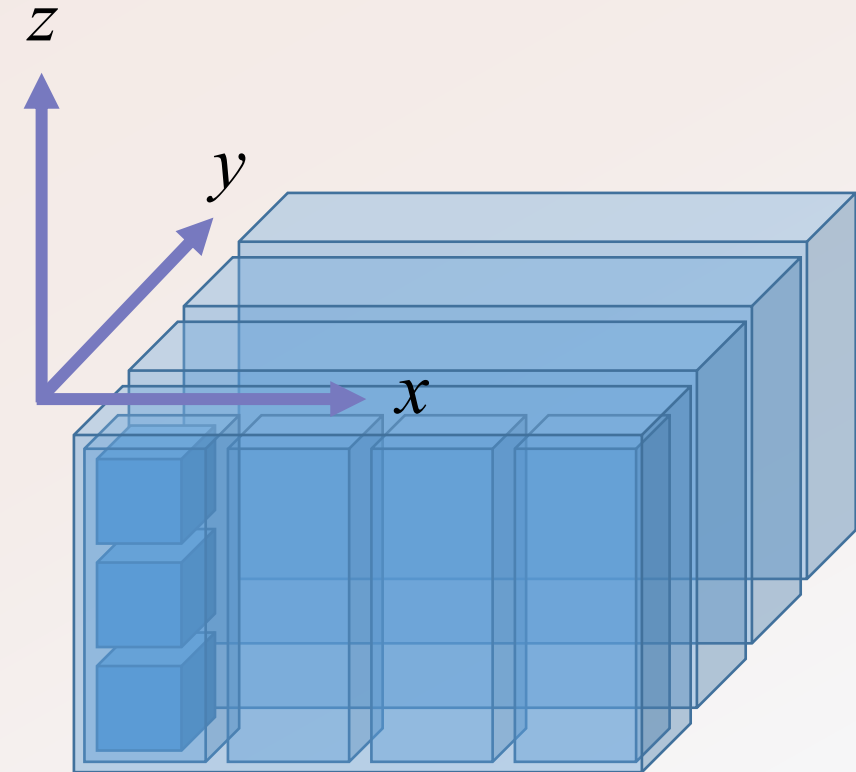
ICRP110PhantomConstruction.cc

```
G4VPhysicalVolume* ICRP110PhantomConstruction::Construct()
{
    new G4PVR Replica(yRepName, logYRep, fContainer_logic, kYAxis, fNVoxelY,
fVoxelHalfDimY*2.);

    new G4PVR Replica(xRepName, logXRep, logYRep, kXAxis, fNVoxelX,
fVoxelHalfDimX*2.);

    ICRP110PhantomNestedParameterisation* param = new
ICRP110PhantomNestedParameterisation(halfVoxelSize, pMaterials);

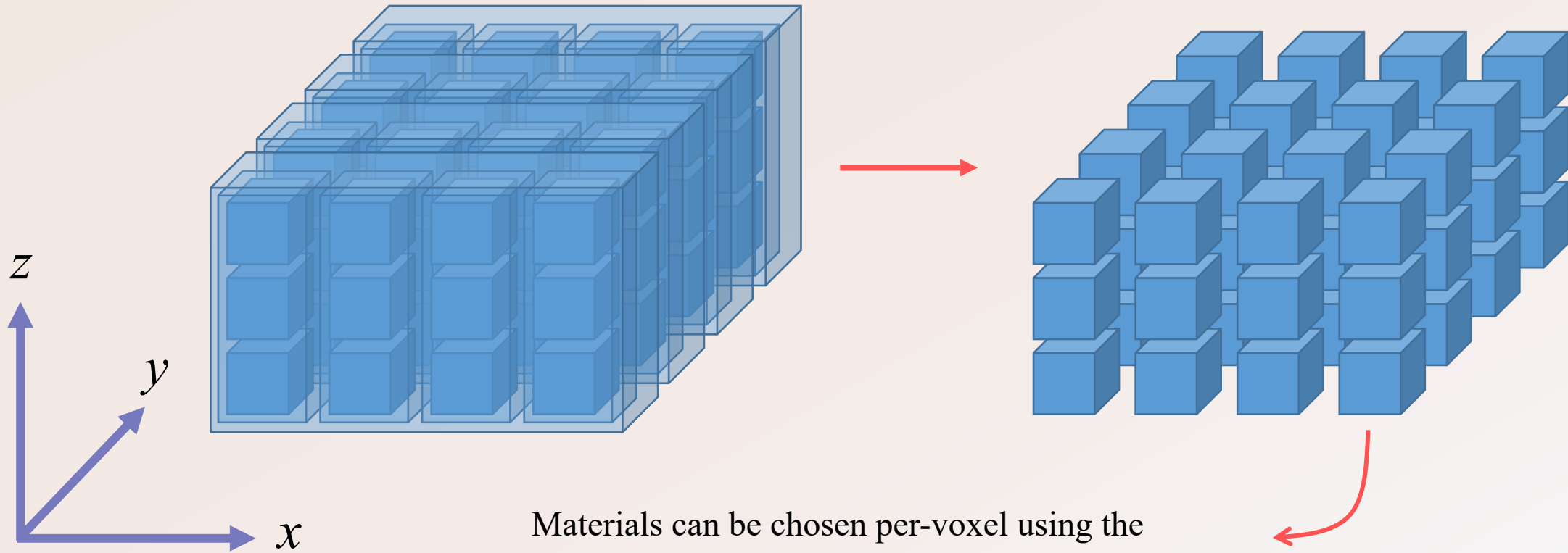
    new G4PVParameterised("phantom", // their name
        logicVoxel, // their logical volume
        logXRep, // Mother logical volume
        kZAxis, // Are placed along this axis
        fNVoxelZ, // Number of cells
        param); // Parameterisation
}
```



⁸ Large et. al., 2020. *Journal of Physics: Conference Series (MMND ITRO 2020)*

ICRP110 Phantom Implementation

- Due to the nested parameterisation, the result is a *voxel* structure:

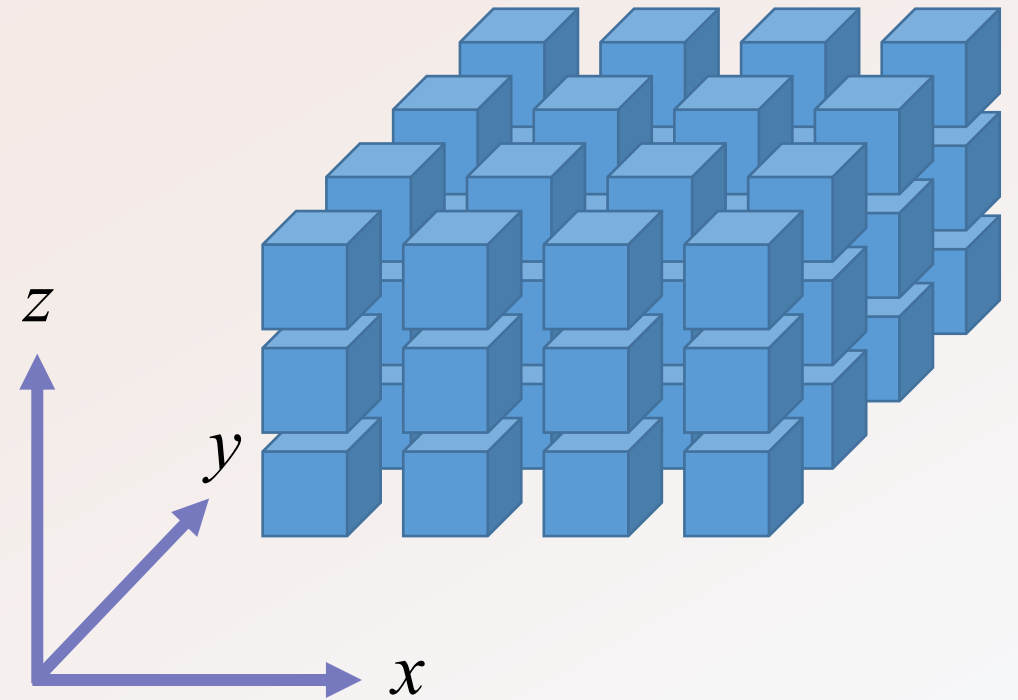


Materials can be chosen per-voxel using the *ComputeMaterial* method of *G4VNestedParameterisation*

ICRP110 Phantom Implementation

- The voxels can be identified using the copy number of each volume

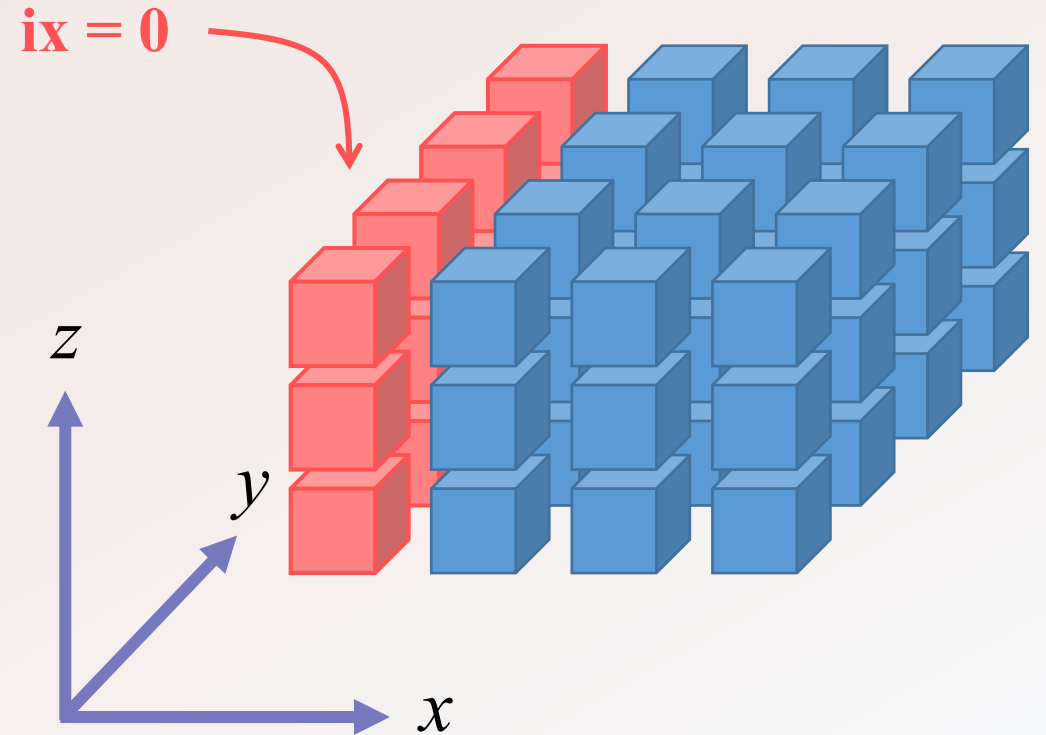
```
G4Material* ICRP110PhantomNestedParameterisation::  
ComputeMaterial(G4VPhysicalVolume* physVol, const G4int  
iz, const G4Touchable* parentTouch)  
{  
    G4int ix = parentTouch->GetCopyNumber(0);  
    G4int iy = parentTouch->GetCopyNumber(1);  
    G4int iz = physVol->GetCopyNo();  
    ...  
    return material;  
}
```



ICRP110 Phantom Implementation

- The voxels can be identified using the copy number of each volume

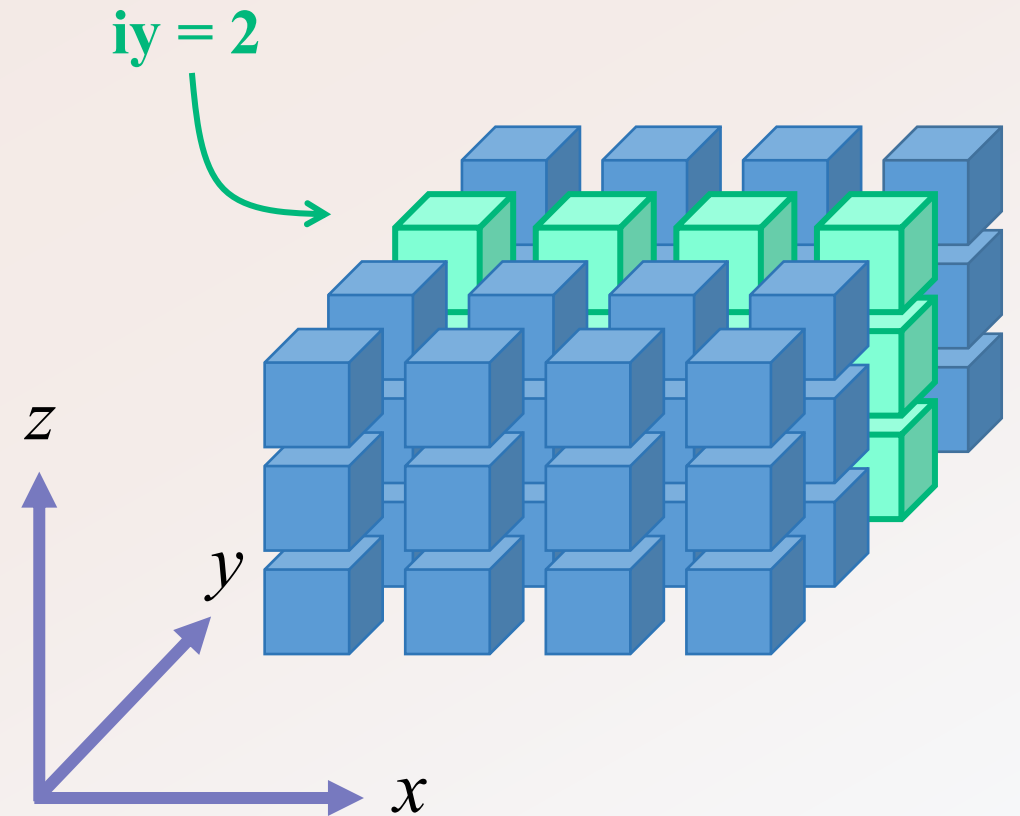
```
G4Material* ICRP110PhantomNestedParameterisation::  
ComputeMaterial(G4VPhysicalVolume* physVol, const G4int  
iz, const G4Touchable* parentTouch)  
{  
    G4int ix = parentTouch->GetCopyNumber(0);  
    G4int iy = parentTouch->GetCopyNumber(1);  
    G4int iz = physVol->GetCopyNo();  
    ...  
    return material;  
}
```



ICRP110 Phantom Implementation

- The voxels can be identified using the copy number of each volume

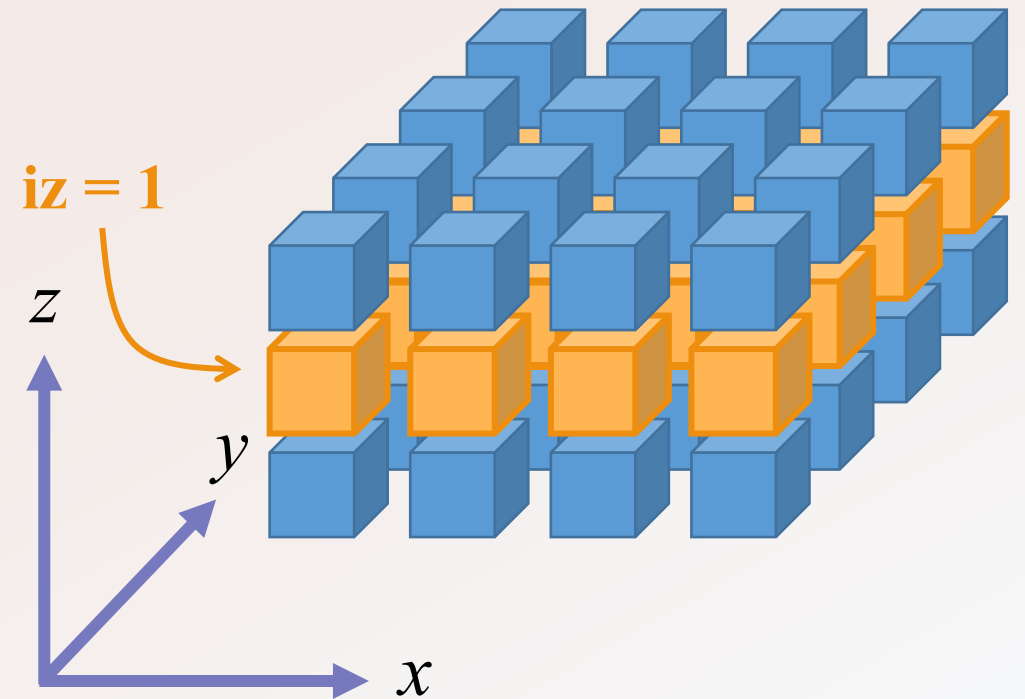
```
G4Material* ICRP110PhantomNestedParameterisation::  
ComputeMaterial(G4VPhysicalVolume* physVol, const G4int  
iz, const G4Touchable* parentTouch)  
{  
    G4int ix = parentTouch->GetCopyNumber(0);  
    G4int iy = parentTouch->GetCopyNumber(1);  
    G4int iz = physVol->GetCopyNo();  
    ...  
    return material;  
}
```



ICRP110 Phantom Implementation

- The voxels can be identified using the copy number of each volume

```
G4Material* ICRP110PhantomNestedParameterisation::  
ComputeMaterial(G4VPhysicalVolume* physVol, const G4int  
iz, const G4Touchable* parentTouch)  
{  
    G4int ix = parentTouch->GetCopyNumber(0);  
    G4int iy = parentTouch->GetCopyNumber(1);  
    G4int iz = physVol->GetCopyNo();  
    ...  
    return material;  
}
```



ICRP110 Phantom Implementation

The material of the individual voxels is handled by
ICRP110PhantomNestedParameterisation

ICRP110PhantomNestedParameterisation.cc

```
G4Material* ICRP110PhantomNestedParameterisation::
ComputeMaterial(G4VPhysicalVolume* physVol, const G4int iz, const G4VTouchable*
parentTouch)
{
    G4int ix = parentTouch -> GetReplicaNumber(0);
    G4int iy = parentTouch -> GetReplicaNumber(1);

    G4int copyID = ix + fnX*iy + fnX*fnY*iz;
    std::size_t matIndex = GetMaterialIndex(copyID);
    static G4Material* mate = nullptr;
    mate = fMaterials[matIndex];

    return mate;
}
```

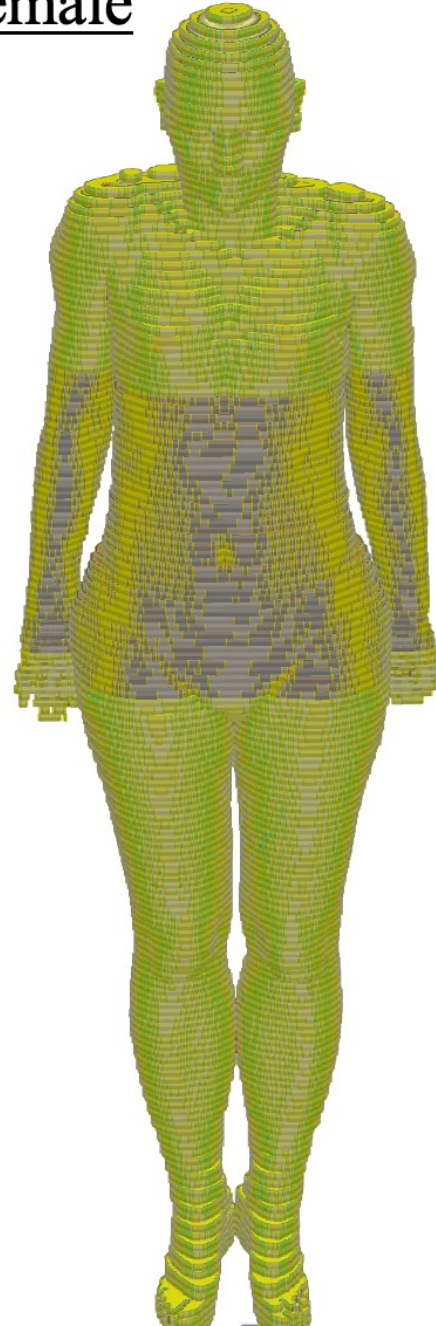
This is a unique integer for each
voxel

fMaterials stores the materials
for each organ

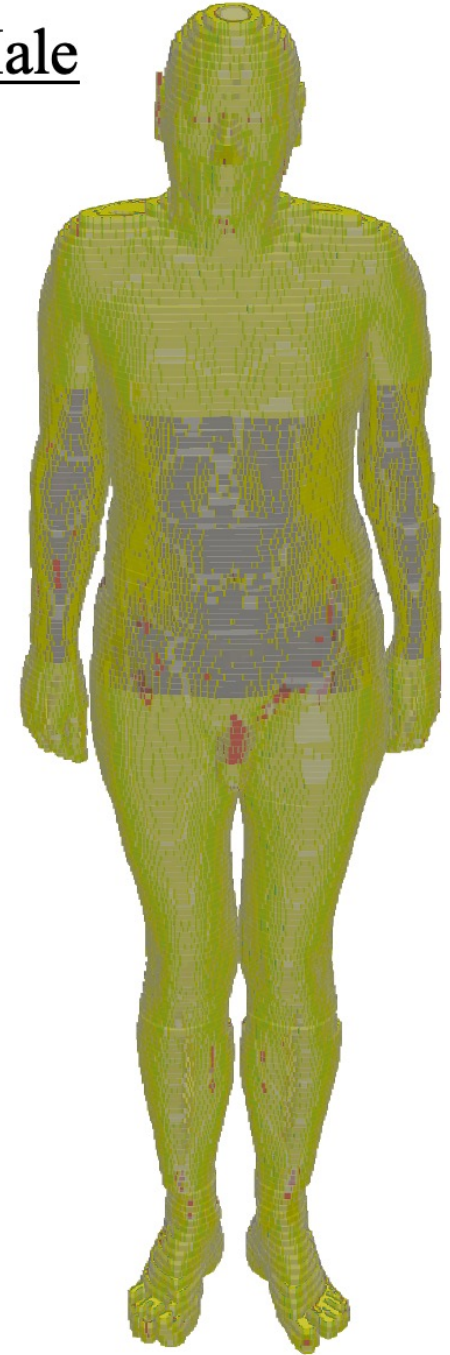
ICRP110 Data

- Each slice file is a different layer of voxels
- The voxel nature of the phantom makes it easy to select specific slices

Female

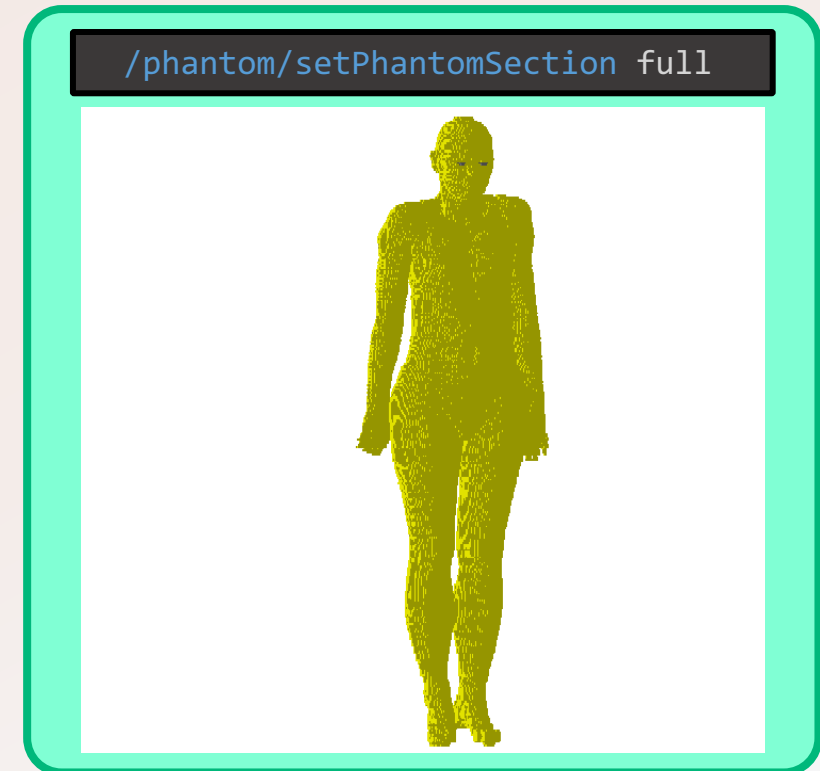
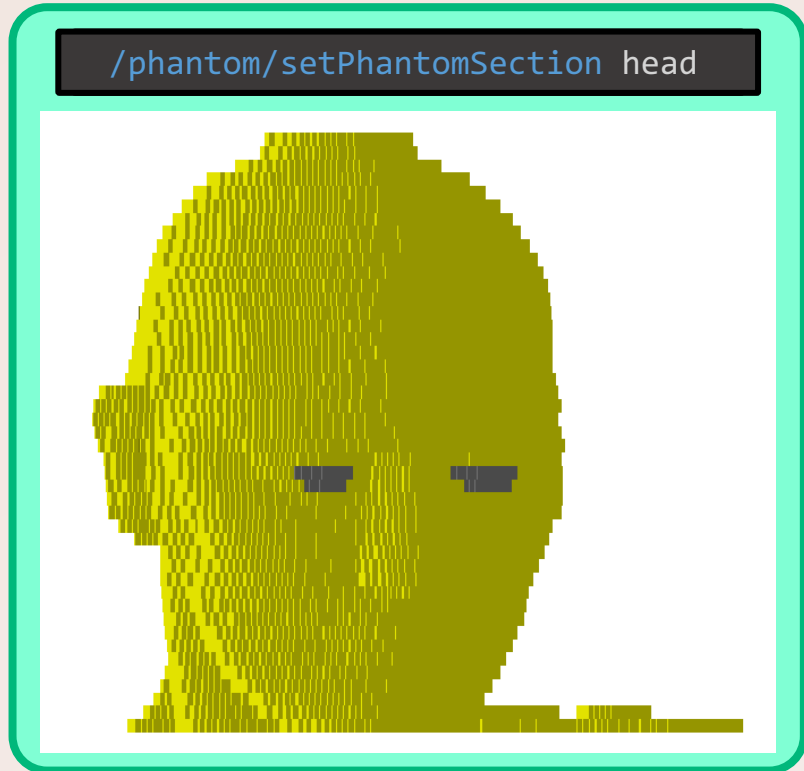


Male



ICRP110 Sections

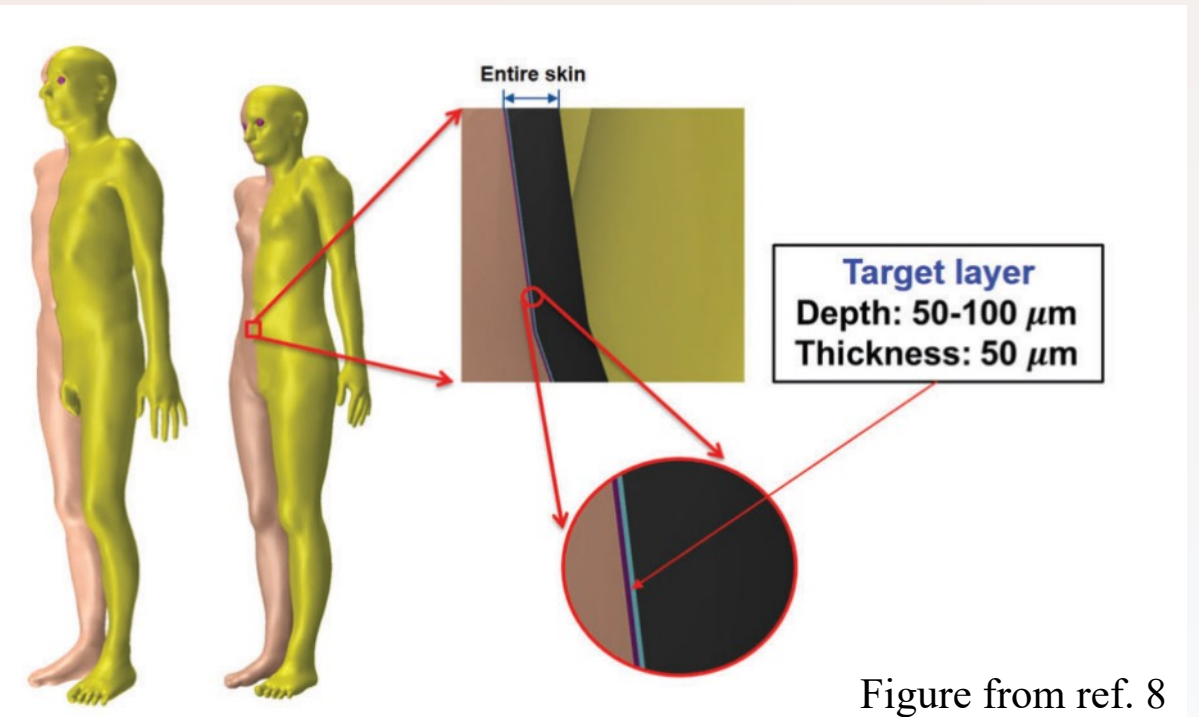
- The included macro files allow for easy implementation of specific sections:



- Can also select custom slices by modifying the number of z slices and the data files in the metadata file

ICRP145 Phantom

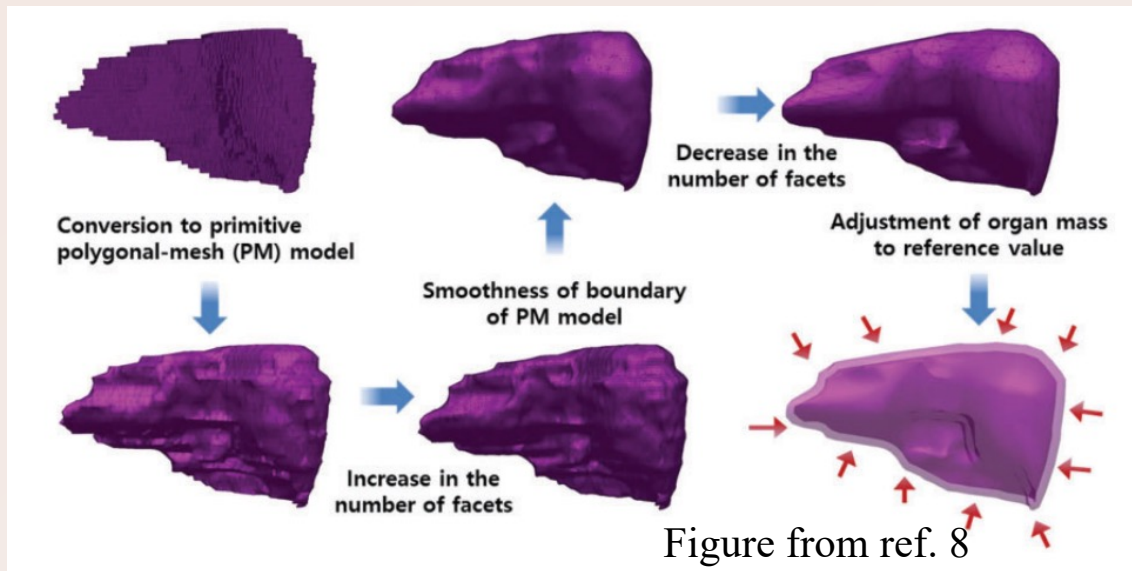
- To overcome limited voxel resolution, tetrahedral mesh phantoms were introduced in ICRP Report 145⁸
- In this phantom:
 - All organs are completely enclosed (including the skin)
 - Detailed models of tubular intestines, spinal structures, lymphatic nodes, eye lens', skin layers



⁸ ICRP, 2009. *Annals of the ICRP* ICRP 49(3)

ICRP145 Phantom

The tetrahedral mesh phantoms were generated from the voxel phantoms using a smoothing and adjustment process:



Doses in each organ computed as standard output:

```

=====
Run #0 / Number of event processed : 10000000
=====
organ ID |      Organ Mass (g)      Dose (Gy/source)      Relative Error
100 |          8.683          1.823e-17          0.214
200 |          8.683          2.226e-17          0.184
300 |           0.022          1.212e-17          0.623
301 |           0.090          1.298e-17          0.594
302 |           0.028          1.613e-17          0.553
303 |         11.291          2.867e-17          0.163
400 |           0.141          3.189e-17          0.582
401 |           0.390          1.916e-17          0.400
402 |           0.098          1.795e-17          0.367
403 |           0.049          2.251e-17          0.450
404 |           0.098          2.337e-17          0.340
405 |         28.808          2.232e-17          0.105
=====

```

ICRP145 Data Definitions

- The data files consist of:

Vertices File

.node

```
1279642 3 0 0
0 1.728173 0.274099 33.475464
1 1.550969 0.481751 33.402969
2 1.788876 0.210670 33.374435
3 1.819830 0.170031 33.444263
4 2.168805 3.718461 33.734196
5 2.124705 3.613879 33.695755
6 2.047916 3.682885 33.755173
7 2.105053 3.762564 33.829369
8 2.268390 3.746360 33.721901
9 2.237944 3.665057 33.678017
10 1.512970 3.144052 34.097740
11 1.445530 2.994499 34.030819
12 1.479287 3.046279 34.258648
```

Vertex
ID

x, y and z position

Tetrahedra File

.ele

```
8582677 4 1
0 1226007 1148977 1225948 1149037 12501
1 901017 459351 901018 459350 11700
2 669624 649462 669602 649482 7401
3 588413 589616 588414 589617 5500
4 1253585 73801 1253586 1253584 11700
5 797418 642003 797417 642234 11700
6 712743 707964 712738 707966 11700
7 1136520 1092753 1136510 1135500 12400
8 896817 896836 896823 854111 10700
9 248688 248687 868295 248689 11600
10 804387 802611 804381 804383 9900
11 527654 471133 527560 527563 4900
12 960713 975965 961002 961003 10900
```

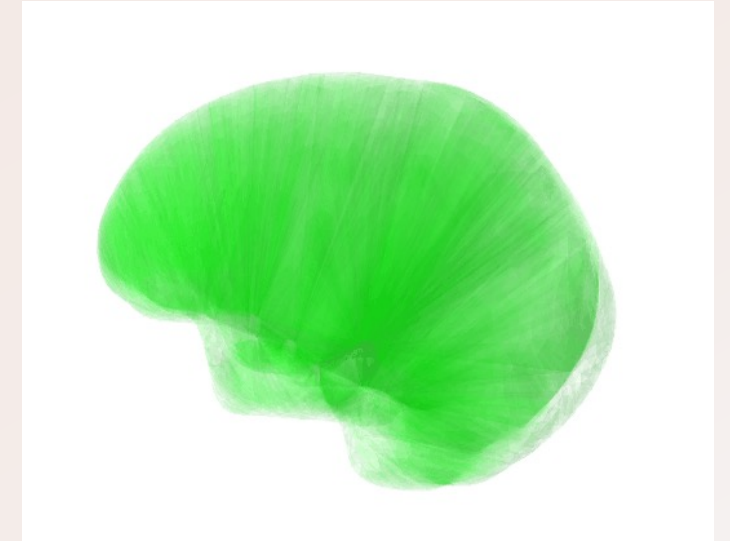
Tet.
ID

IDs of the vertices of
the tetrahedra

Organ
ID

ICRP145 Data

- The data is imported through the *TETModelImport* class
- Through small modifications, the import can be restricted from tetrahedra of certain organ ids or positions
- The *organ id* of a volume can be obtained using the tetrahedron *copy number*



```
void SteppingAction::UserSteppingAction(const G4Step* step)
{
    ...
    G4int copyNo = step->GetPreStepPoint()->GetTouchable()->GetCopyNumber();
    G4int organId = fTETData->GetMaterialIndex(copyNo);

    if (organId == 6100)
    {
        // This is in the brain, do something...
    }
}
```

Bone Dose Computations

- All phantoms listed do not directly segment active (red) bone marrow
- Instead, the ICRP Report 116⁹ describes an estimation of the dose to active marrow using doses to the spongiosa:
- For each bone site x the total active marrow dose $D_{skel}(AM)$ is the total dose to the spongiosa at each site $D(SP, x)$ scaled by the fractional mass of active marrow at each site $m(AM, x)/m(AM)$:

$$D_{skel}(AM) = \sum_x \frac{m(AM, x)}{m(AM)} D(SP, x)$$

⁹ ICRP, 2010. *Annals of the ICRP* **40**(2-5)

Bone Dose Computations

- Active marrow masses available in ICRP 110 and ICRP 116:

Table 3.2. Skeletal tissue masses in the ICRP reference adult male and adult female computational phantoms.

Organ	Bone site	Reference adult male				Reference adult female			
		Active marrow		Endosteum		Active marrow		Endosteum	
		Mass (g)	Mass (%)	Mass (g)	Mass (%)	Mass (g)	Mass (%)	Mass (g)	Mass (%)
14	Humeri, upper half – spongiosa	26.9	2.3	9.41	1.7	20.7	2.3	7.16	1.8
15	Humeri, upper half – medullary cavities			0.19	0.0			0.14	0.0
17	Humeri, lower half – spongiosa			11.25	2.1			8.32	2.0
18	Humeri, lower half – medullary cavities			0.25	0.0			0.19	0.0
20	Lower arm bones – spongiosa			16.31	3.0			12.03	3.0
21	Lower arm bones – medullary cavities			0.09	0.0			0.07	0.0
23	Wrists and hands – spongiosa			12.50	2.3			7.10	1.7
25	Clavicles – spongiosa	9.3	0.8	2.50	0.5	7.2	0.8	1.90	0.5
27	Cranium – spongiosa	88.9	7.6	83.40	15.3	68.4	7.6	64.20	15.8
29	Femora, upper half – spongiosa	78.4	6.7	43.34	8.0	60.3	6.7	33.53	8.2
30	Femora, upper half – medullary cavities			0.86	0.2			0.67	0.2
32	Femora, lower half – spongiosa			47.83	8.8			23.67	5.8
33	Femora, lower half – medullary cavities			0.67	0.1			0.33	0.1
35	Lower leg bones – spongiosa			87.38	16.1			79.91	19.6
36	Lower leg bones – medullary cavities			5.02	0.9			4.59	1.1
38	Ankles and feet – spongiosa			42.20	7.8			24.40	6.0
40	Mandible – spongiosa	9.4	0.8	2.00	0.4	7.2	0.8	1.60	0.4
42	Pelvis – spongiosa	205.2	17.5	51.70	9.5	157.5	17.5	39.70	9.7
44	Ribs – spongiosa	188.8	16.1	29.80	5.5	144.9	16.1	22.90	5.6
46	Scapulae – spongiosa	32.8	2.8	9.80	1.8	25.2	2.8	7.60	1.9
48	Cervical spine – spongiosa	45.6	3.9	11.50	2.1	35.1	3.9	8.80	2.2
50	Thoracic spine – spongiosa	188.8	16.1	26.90	4.9	144.9	16.1	20.60	5.1
52	Lumbar spine – spongiosa	143.9	12.3	23.40	4.3	110.7	12.3	18.00	4.4
54	Sacrum – spongiosa	115.9	9.9	20.60	3.8	89.1	9.9	15.80	3.9
56	Sternum – spongiosa	36.3	3.1	5.50	1.0	27.9	3.1	4.30	1.1
	Totals	1170.2	100	544.4	100	899.1	100	407.50	100

Source: ICRP, 2009. Adult reference computational phantoms. ICRP Publication 110. Ann. ICRP 39(2).

⁹ ICRP, 2010. *Annals of the ICRP* 40(2-5)

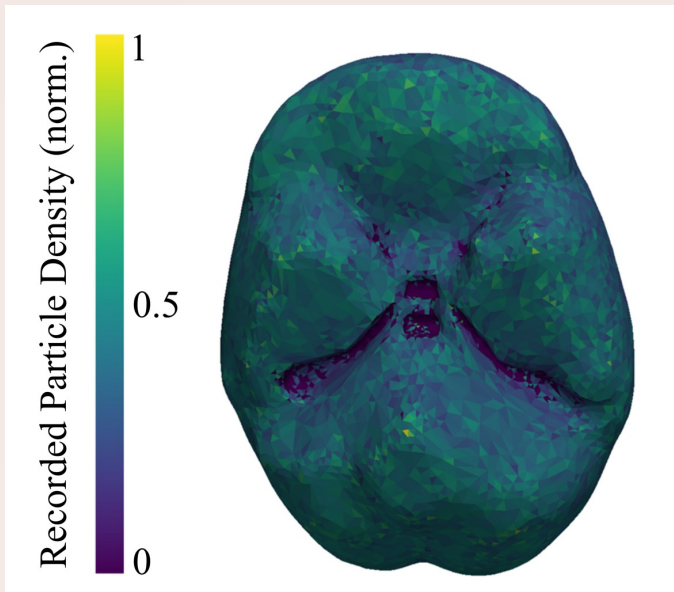
Extra Considerations

- The tetrahedral (volume) phantom geometry has large *memory* requirements ($\sim 11 \text{ GB}^{10}$)
- Supplementary materials provided with the ICRP145 report also gives a *polygonal* (surface) mesh
 - Can be useful for visualisation or manipulation using other software
- The tetrahedral mesh compared to the polygonal mesh ¹⁰:
 - More efficient for particle transport (~ 2600 times faster)
 - Less time for initialisation (~ 0.5 times)
 - Requires more memory (11 GB vs 1.3 GB)

¹⁰ Han et. al., 2020. *Journal of Radiological Protection*, **40**(4)

Extra Considerations

- Polygonal meshes visualized:
- Since the tetrahedral mesh is generated from the polygonal mesh, the polygonal mesh can be used for surface calculations



Male



Female

