



#### Phasing and Calibration of the Main Linac Cryomodule Cavities for the CBETA Energy Recover Linac

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## **Phasing/Calibration Goal**

- In our model, each cavity has certain voltage and phase settings
- In the control system, we set voltage and phase values
- Goal: make the voltage/phase settings set in the control system correspond to what we set in the model



## The CBETA MLC Linac

- Six 1.3 GHz cavities
- Beam injected at 6 MeV
- 36 MeV design energy gain, about 6 MeV/cavity
- BPMs at the entrance and exit of the linac
  - Capable of precise beam arrival measurement relative to 1.3 GHz reference



### **Method Overview**

- Measure time of flight
- BPMs at entrance and exit of linac
- One cavity on at a time
- Voltage set to a significant fraction of beam energy
- Swing phase through 360°
- Fit measurements to model
  - Scaling factor for voltage
  - Offset for phase



## Model: Cavity

- On-axis cavity field from finite-element cavity model  $\frac{dE}{ds} = qVG(s)\cos(\omega t + \phi)$ • Normalize G(s) for v = c particle:  $\int G(s)\cos\left(\frac{\omega s}{c} + \phi\right)ds = \cos(\phi + \phi_c)$
- Define phase  $\phi_0$  based on 6 MeV constant-velocity particle  $\int G(s) \cos\left(\frac{\omega s}{\beta_0 c} + \phi + \phi_0\right) ds = A \cos \phi$



### Model: Linac

- In our accelerator model, keep the same reference energy for timing through the entire linac for each pass
  - Design energy at the entrance to the linac for that pass
  - Reference timing doesn't change when we change machine settings
  - · Calibration done here applies directly to model
- Components at known longitudinal positions
  - $s_1...s_6$  for cavities (relative to s = 0 in cavity model)
  - $s_0$  and  $s_7$  for entrance and exit BPMs



#### Model: Arrival Time Difference

- Integrate ODEs within cavity from  $s_a$  to  $s_b$ , with  $E(s_a) = E_0$  and  $t(s_a) = s_a/\beta_0 c$ :  $\frac{dt}{ds} = \frac{E}{c\sqrt{E^2 - (mc^2)^2}}$   $\frac{dE}{ds} = qVG(s)\cos(\omega t + \phi + \phi_0)$
- Result is  $t(s_b) = t_m(V, \phi, E_0)$  and  $E(s_b) = E_m(V, \phi, E_0)$



### **Model: Arrival Time Difference**

• Arrival time difference between accelerated particle for cavity at *s* and particle with cavities off  $T(V, \phi, E_0, s)$  $(s_7 - s - s_b)E_m(V, \phi, E_0) + (s_7 - s - s_a)E_0$ 

$$= t_m(V,\phi,E_0) + \frac{(V,\phi,E_0)^2 - (mc^2)^2}{c\sqrt{E_m(V,\phi,E_0)^2 - (mc^2)^2}} + \frac{(V,\phi,E_0)^2}{c\sqrt{(E_0)^2 + (mc^2)^2}}$$



### The Measurement and Fit

- Measure arrival time difference between entrance and exit BPMs
  Mathematically unnecessary, but removes noise
- Make a high precision measurement of time  $T_0$  with cavities off
- Turn cavity *i* on, scan evenly spaced points in phase setting  $\psi_k$ , possibly at more than one voltage setting  $V_l$ , measure times  $T_{kl}$
- Find phase offset  $\phi_i$ , scaling factor  $\lambda_i$ , and incoming energy  $E_0$  that minimize (fit all cavities together to get common  $E_0$ )

$$\sum_{ikl} [T_{kl} - T_0 - T(\lambda_i V_l, \phi_i + \psi_k, E_0, s_i)]^2$$



#### Fast, Precise, and Robust Calculation: Newton's Method

• General least-squares problem like ours:

$$f(\vec{p}) = \sum_{j} \left[ T_j(\vec{p}) - t_j \right]^2$$

• Minimum occurs when

$$0 = \frac{\partial f}{\partial \vec{p}} = \sum_{j} \frac{\partial T_{j}}{\partial \vec{p}} \left[ T_{j}(\vec{p}) - t_{j} \right]$$

• Apply Newton's method to this: very fast and robust, will also need  $\partial^2 f / \partial p_i \partial p_j$  and therefore  $\partial^2 T_k / \partial p_i \partial p_j$ , plus a good initial guess



# **Computing Derivatives**

- Only nontrivial derivatives to compute are for  $t_m$  and  $E_m$
- General differential equation for  $\vec{z}(\vec{z}_0, \vec{p}, s), \vec{z}(\vec{z}_0, \vec{p}, 0) = \vec{z}_0$ :  $\frac{d\vec{z}}{ds} = \vec{g}(\vec{z}(\vec{z}_0, \vec{p}, s), \vec{p}, s)$
- Can write differential equations for derivative:  $\frac{d}{ds}\frac{\partial z_i}{\partial p_j} = \sum_k \frac{\partial g_i}{\partial z_k}\frac{\partial z_k}{\partial p_j} + \frac{\partial g_i}{\partial p_j} \frac{d}{ds}\frac{\partial z_i}{\partial z_{0j}} = \sum_k \frac{\partial g_i}{\partial z_k}\frac{\partial z_k}{\partial z_{0j}} \left. \frac{\partial z_i}{\partial p_j} \right|_0 = 0 \left. \frac{\partial z_i}{\partial z_{0j}} \right|_0 = \delta_{ij}$
- Similar equations for second derivative
- Derivatives of  $\vec{g}$  with respect to parameters are easy for this system
- Thus find all derivatives with coupled ODEs over a single cavity



### **Initial Guess**

- Use data points with maximum and minimum arrival times  $T_+$
- Guess phase offset  $\phi_i$  assuming these are trough/crest
- For  $\lambda_i$  and  $E_0$ , assume all energy gained at cavity center, solve  $T_{\pm} T_0 \approx \frac{(s_7 s_i)(E_0 \pm \lambda_i V_i)}{c\sqrt{(E_0 \pm \lambda_i V_i)^2 (mc^2)^2}} \frac{(s_7 s_i)E_0}{c\sqrt{(E_0)^2 (mc^2)^2}}$ • Guess: expand to second order in  $\lambda_i$ , solving for  $E_0$  and  $\lambda_i$   $\frac{c(T_{\pm} - T_0)}{s_7 - s_i} \approx \pm \frac{\lambda_i V_i (mc^2)^2}{[(E_0)^2 - (mc^2)^2]^{3/2}} + \frac{3E_0 (mc^2)^2 \lambda_i^2 V_i^2}{[(E_0)^2 - (mc^2)^2]^{5/2}}$



## Sample Run

- 10 degree steps, 3000 kV and 4000 kV settings
- First and last cavity shown
- Errors dominated by systematics: model, measurement
- Uncertainties computable: phase uncertainties between 0.04° and 0.21°, calibration from 0.17% to 0.50%, E<sub>0</sub> 6.6 keV





### **Practical Details**

- Beam going off-axis messes up time of flight measurement, but difficult to quantify exactly how
  - We measured the MLC misalignment and steered the beam to the center
- The method did not work well for our injector cryomodule
  - Steering by cavities was severe
  - Low energy makes beam transmission for all phases difficult
- In practice used 30° steps and one voltage, only calibrating phases and checking injection energy
  - RF phases relative to gun reset on each machine start/trip



#### **Practical Details**

- Actual voltage assumed to be linear in control system voltage
- Voltage calibration *should* not be needed very often
- But we did have a slow drift in actual voltage, likely because our control readback did not accurately reflect the voltage
- Algorithm fast & robust: never failed unless data taking failed





## Summary

- Created a method to quickly calibrate phases and voltages of our main linac cavities by scanning phases of cavities one at a time with injected beam
- Using a good cavity model, Newton's method, and a good initial guess, the computation runs very quickly and never failed
- Careful cavity phase calibration and RF modeling enabled 4-pass energy recovery in CBETA



