



#### **Phasing and Calibration of the Main Linac Cryomodule Cavities for the CBETA Energy Recover Linac**

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## **Phasing/Calibration Goal**

- In our model, each cavity has certain voltage and phase settings
- In the control system, we set voltage and phase values
- Goal: make the voltage/phase settings set in the control system correspond to what we set in the model



## **The CBETA MLC Linac**

- Six 1.3 GHz cavities
- Beam injected at 6 MeV
- 36 MeV design energy gain, about 6 MeV/cavity
- BPMs at the entrance and exit of the linac
	- Capable of precise beam arrival measurement relative to 1.3 GHz reference



### **Method Overview**

- Measure time of flight
- BPMs at entrance and exit of linac
- One cavity on at a time
- Voltage set to a significant fraction of beam energy
- Swing phase through 360°
- Fit measurements to model
	- Scaling factor for voltage
	- Offset for phase



## **Model: Cavity**

- On-axis cavity field from finite-element cavity model  $dE$  $\frac{ds}{dt}$  $= qV G(s) \cos(\omega t + \phi)$ • Normalize  $G(s)$  for  $v = c$  particle:  $\int G(s) \cos$  $\omega$  $\mathcal{C}_{\mathcal{C}}$  $+ \phi$ ) ds = cos( $\phi + \phi_c$ )
- Define phase  $\phi_0$  based on 6 MeV constant-velocity particle  $\int G(s) \cos$  $\omega$  $\beta_0 c$  $+ \phi + \phi_0$  |  $ds = A \cos \phi$



### **Model: Linac**

- In our accelerator model, keep the same reference energy for timing through the entire linac for each pass
	- Design energy at the entrance to the linac for that pass
	- Reference timing doesn't change when we change machine settings
	- Calibration done here applies directly to model
- Components at known longitudinal positions
	- $s_1...s_6$  for cavities (relative to  $s = 0$  in cavity model)
	- $s_0$  and  $s_7$  for entrance and exit BPMs



#### **Model: Arrival Time Difference**

- Integrate ODEs within cavity from  $s_a$  to  $s_b$ , with  $E(s_a) = E_0$  and  $t(s_a) = s_a/\beta_0 c$ :  $dt$  $\frac{ds}{dt}$ =  $c\sqrt{E^2-(mc^2)^2}$  $dE$  $\overline{ds}$  $= qV G(s) \cos(\omega t + \phi + \phi_0)$
- Result is  $t(s_h) = t_m(V, \phi, E_0)$  and  $E(s_h) = E_m(V, \phi, E_0)$



### **Model: Arrival Time Difference**

• Arrival time difference between accelerated particle for cavity at s and particle with cavities off  $T(V, \phi, E_0, s)$  $= t_m(V, \phi, E_0) + \frac{(s_7 - s - s_b)E_m(V, \phi, E_0)}{E_m(V, \phi, E_0)} + \frac{(s_7 - s - s_a)E_0}{E_m(V, E_0)}$ 

$$
L_m(V,\varphi,L_0) = \frac{1}{c\sqrt{E_m(V,\phi,E_0)^2 - (mc^2)^2}} + \frac{1}{c\sqrt{(E_0)^2 + (mc^2)^2}}
$$



### **The Measurement and Fit**

- Measure arrival time difference between entrance and exit BPMs
	- Mathematically unnecessary, but removes noise
- Make a high precision measurement of time  $T_0$  with cavities off
- Turn cavity *i* on, scan evenly spaced points in phase setting  $\psi_k$ , possibly at more than one voltage setting  $V_i$ , measure times  $T_{ki}$
- Find phase offset  $\phi_i$ , scaling factor  $\lambda_i$ , and incoming energy  $E_0$  that minimize (fit all cavities together to get common  $E_0$ )

$$
\sum_{ikl} [T_{kl} - T_0 - T(\lambda_i V_l, \phi_i + \psi_k, E_0, s_i)]^2
$$



#### **Fast, Precise, and Robust Calculation: Newton's Method**

• General least-squares problem like ours:

$$
f(\vec{p}) = \sum_j [T_j(\vec{p}) - t_j]^2
$$

• Minimum occurs when

$$
0 = \frac{\partial f}{\partial \vec{p}} = \sum_{j} \frac{\partial T_j}{\partial \vec{p}} [T_j(\vec{p}) - t_j]
$$

• Apply Newton's method to this: very fast and robust, will also need  $\partial^2 f/\partial p_i \partial p_j$  and therefore  $\partial^2 T_k/\partial p_i \partial p_j$ , plus a good initial guess



# **Computing Derivatives**

- Only nontrivial derivatives to compute are for  $t_m$  and  $E_m$
- General differential equation for  $\vec{z}(\vec{z}_0,\vec{p},s)$ ,  $\vec{z}(\vec{z}_0,\vec{p},0)=\vec{z}_0$ :  $\overline{dz}$  $\overline{ds}$  $= g(z(z_0, p, s), p)$
- Can write differential equations for derivative:  $\frac{a}{\overline{a}}$  $\overline{a}$ s  $\frac{\partial Z_i}{\partial x_i}$  $\sigma p_j$  $= \sum_{k}$  $\frac{\partial g_i}{\partial x_i}$  $\partial Z_k$  $\boldsymbol{dz_k}$  $\mathit{op}_j$  $+\frac{\partial g_i}{\partial n_i}$  $\sigma p_j$  $\frac{a}{\overline{a}}$  $\overline{a}$ s  $\frac{\partial Z_i}{\partial x_i}$  $dz_{0j}$  $= \sum_{k}$  $\frac{\partial g_i}{\partial x_i}$  $\sigma z_k$  $\boldsymbol{dz_k}$  $\sigma z_{0j}$  $\frac{\partial z_i}{\partial n_i}$  $\frac{\partial p_j}{\partial}$  $= 0 \frac{\partial z_i}{\partial z_{0,i}}$  $\left. \frac{\partial z_{0j}}{\partial z_{0j}} \right|_{0}$  $= \delta_i$
- Similar equations for second derivative
- Derivatives of  $\vec{g}$  with respect to parameters are easy for this system
- Thus find all derivatives with coupled ODEs over a single cavity



### **Initial Guess**

 $7 - s_i$ 

- Use data points with maximum and minimum arrival times  $T_+$
- Guess phase offset  $\phi_i$  assuming these are trough/crest
- For  $\lambda_i$  and  $E_0$ , assume all energy gained at cavity center, solve  $T_{\pm} - T_0 \approx$  $\frac{(s_7 - s_i)(E_0 \pm \lambda_i V_i)}{c\sqrt{(E_0 \pm \lambda_i V_i)^2 - (mc^2)^2}} - \frac{(s_7 - s_i)E_0}{c\sqrt{(E_0)^2 - (mc^2)^2}}$ • Guess: expand to second order in  $\lambda_i$ , solving for  $E_0$  and  $\lambda_i$  $c(T_{\pm} - T_0)$  $\approx \pm$  $\lambda_i V_i (mc^2)^2$  $(v_0)^2 - (mc^2)^2]^{3/2}$  $3E_0 (mc^2)^2 \lambda_i^2$  $\frac{l}{l}$ .<br>.<br>.  $(v_0)^2 - (mc^2)^2\frac{5}{2}$



## **Sample Run**

- 10 degree steps, 3000 kV and 4000 kV settings
- First and last cavity shown
- Errors dominated by systematics: model, measurement
- Uncertainties computable: phase uncertainties between 0.04° and 0.21°, calibration from 0.17% to 0.50%,  $E_0$  6.6 keV





### **Practical Details**

- Beam going off-axis messes up time of flight measurement, but difficult to quantify exactly how
	- We measured the MLC misalignment and steered the beam to the center
- The method did not work well for our injector cryomodule
	- Steering by cavities was severe
	- Low energy makes beam transmission for all phases difficult
- In practice used 30° steps and one voltage, only calibrating phases and checking injection energy
	- RF phases relative to gun reset on each machine start/trip



#### **Practical Details**

- Actual voltage assumed to be linear in control system voltage
- Voltage calibration *should* not be needed very often
- But we did have a slow drift in actual voltage, likely because our control readback did not accurately reflect the voltage
- Algorithm fast & robust: never failed unless data taking failed





## **Summary**

- Created a method to quickly calibrate phases and voltages of our main linac cavities by scanning phases of cavities one at a time with injected beam
- Using a good cavity model, Newton's method, and a good initial guess, the computation runs very quickly and never failed
- Careful cavity phase calibration and RF modeling enabled 4-pass energy recovery in CBETA



