

Model-independence in machine-learning-based mass reconstruction for inclusive multi-jet search

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Inclusive multi-jet search

► **Multi-jet final state**

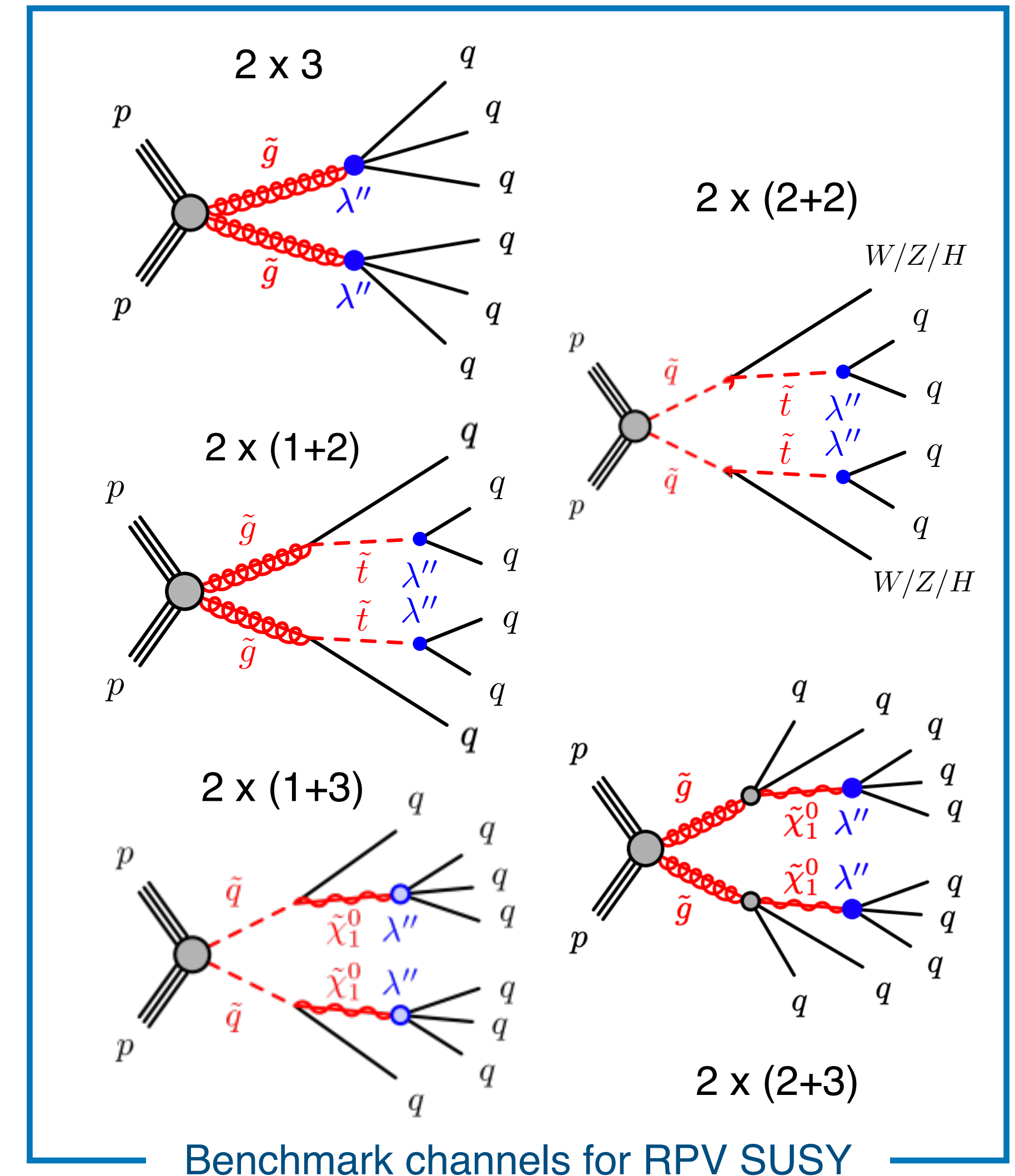
- Final state with multiple quarks
- Can be a portal to variety of BSM
- Especially decays only with light flavor quarks are not well-covered

► **Example: RPV SUSY**

► **Don't limit the target as far as possible**

- Pair production of heavy particles
- Both decay through all hadronic channel

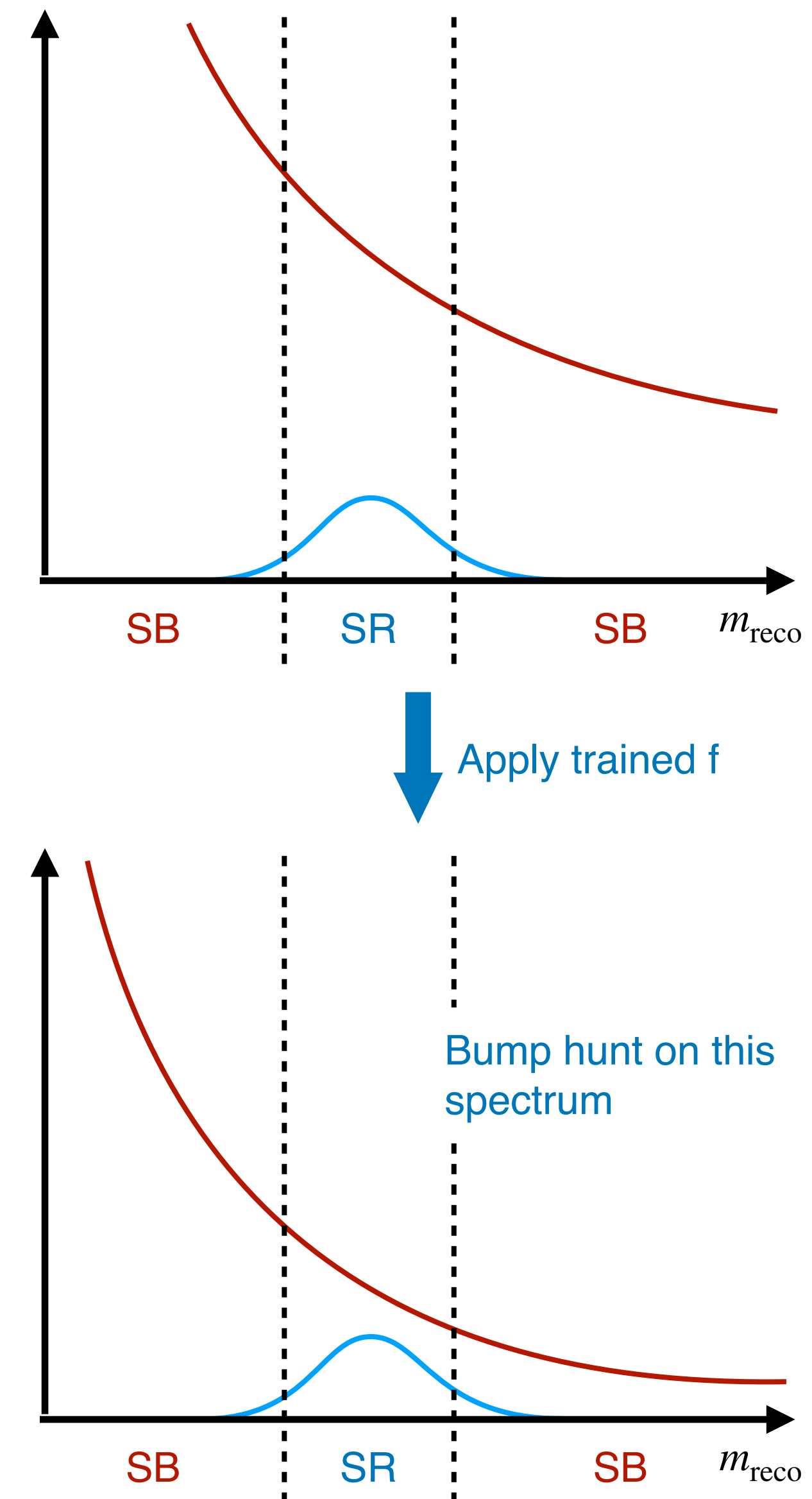
► **Can even cover something not considered yet**



Strategy for inclusive search

► Bump hunting on mass spectrum with the help of **weakly-supervised ML**

- Fully data driven
 - CWoLa [[arXiv:1708.02949](https://arxiv.org/abs/1708.02949)], CATHODE [[arXiv:2109.00546](https://arxiv.org/abs/2109.00546)], CURTAINS [[arXiv:2203.09470](https://arxiv.org/abs/2203.09470)], etc.
 - Data driven weak supervision
 - Pick a data event from either **SB (Side band)** / **SR (Signal region)**
 - Train **SB / SR** classifier f (not signal/background)
 - $f(\text{event}) \mapsto \text{SB}$ or **SR**
 - **Magically, optimal f is equivalent to optimal **signal / background classifier!****
 - Use trained f to enhance significance
 - Do bump hunt on top of that
- ## ► Requirement: signal needs to be localized
- Challenge: **Model-independent sharp reconstructed mass**

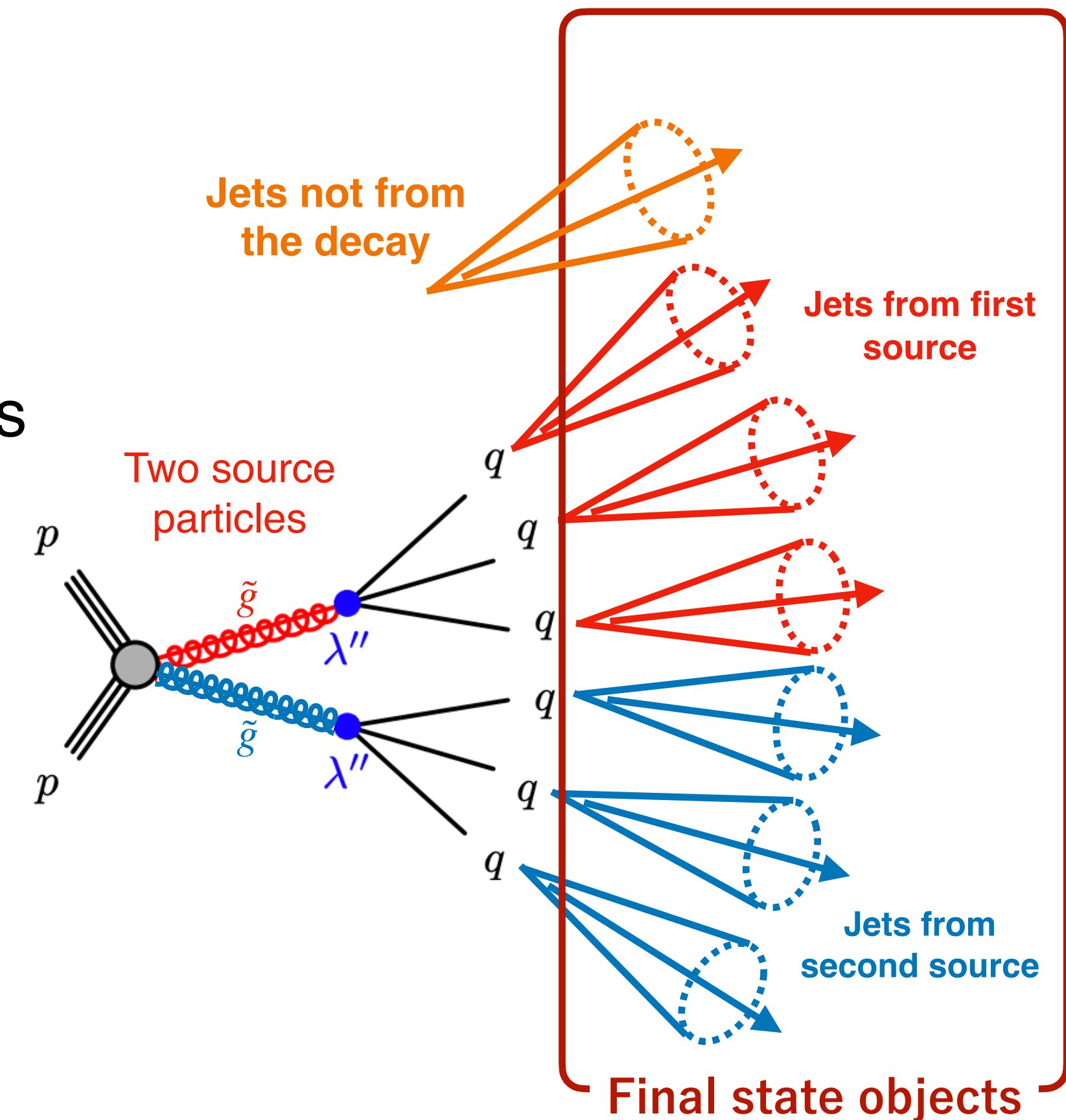


Reconstruction of multi-jet events

► **Today's main topic**

► **Jets - source particle matching**

- To reconstruct the mass, we need the correct combination of jets to build each of the two source particles
- Source particles are the same kind of particle
-> Make two groups of jets so that they look alike
- Some jets may come outside of the decay
-> One additional group (garbage group)
- **Develop jets grouping method based on ML**
 - Challenge: **Model independence**



Input	j_1	j_2	j_3	j_4	j_5	j_6	j_7	j_8	j_9	j_{10}	j_{11}	j_{12}
SUSY 1	1			1		1			1			
SUSY 2		1	1				1				1	
Garbage					1			1		1		1

Training sample dependence: mass dependence

- ▶ **Mass dependence**

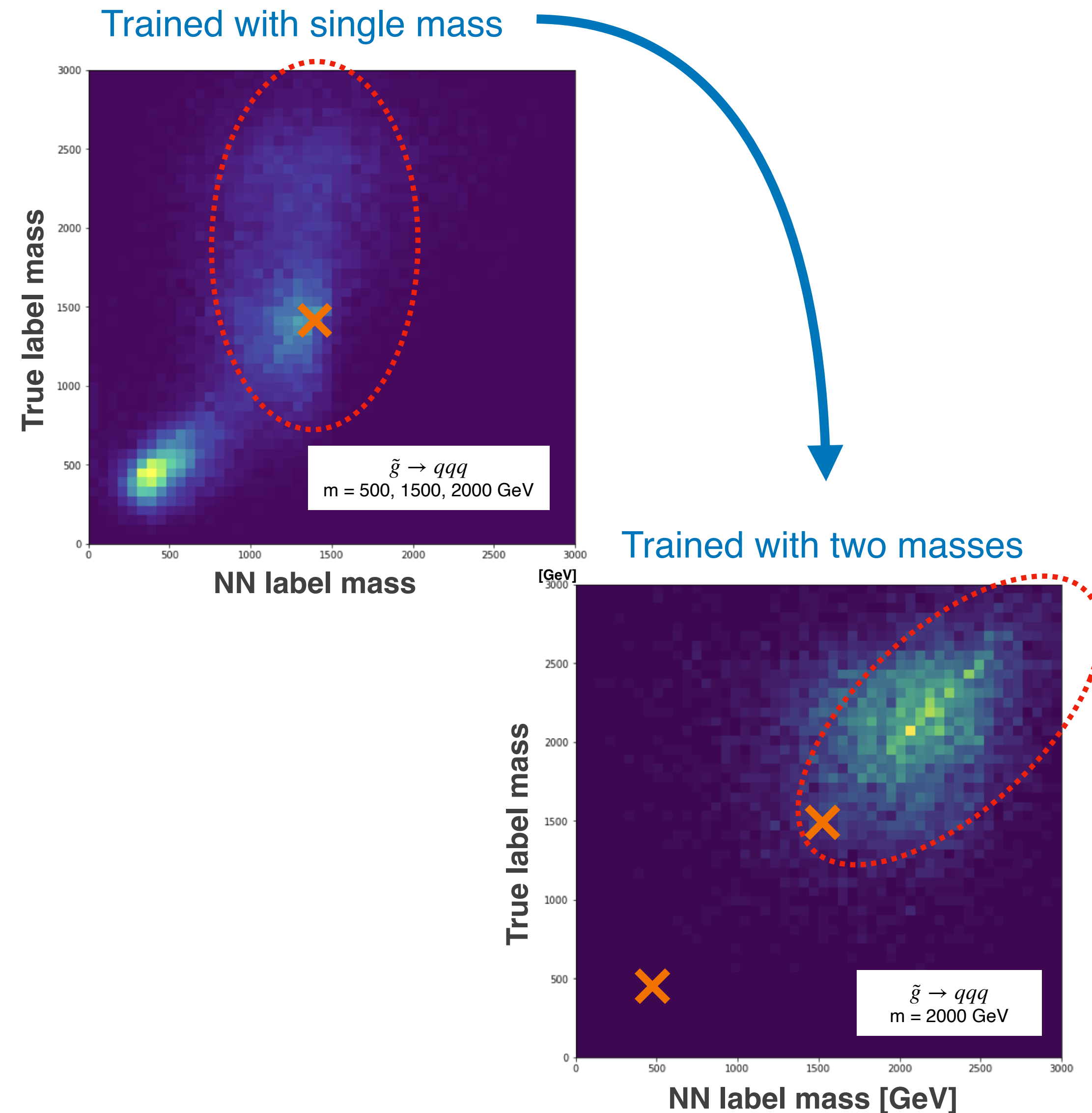
- When trained on single mass...
 - Cannot reconstruct mass higher than the given mass

- ▶ **What if adding other mass in the training?**

- Mixing two masses in the training and test on unknown mass
- **Now NN can reconstruct masses higher than the given mass!**

- ▶ **Just adjusting training sample composition can help mass-independence**

- Single mass
 - > Learns the mass
- Mixed mass
 - > **Learns to make two similar groups of jets**



Training sample dependence: background sculpting

▶ Background sculpting

- NN is trained to reconstruct high mass signals
-> Tends to reconstruct backgrounds in high mass

▶ Can composition adjusting useful in this case too?

- **Yes!**
- Mixing background in the training sample
- **NN learns low mass background**

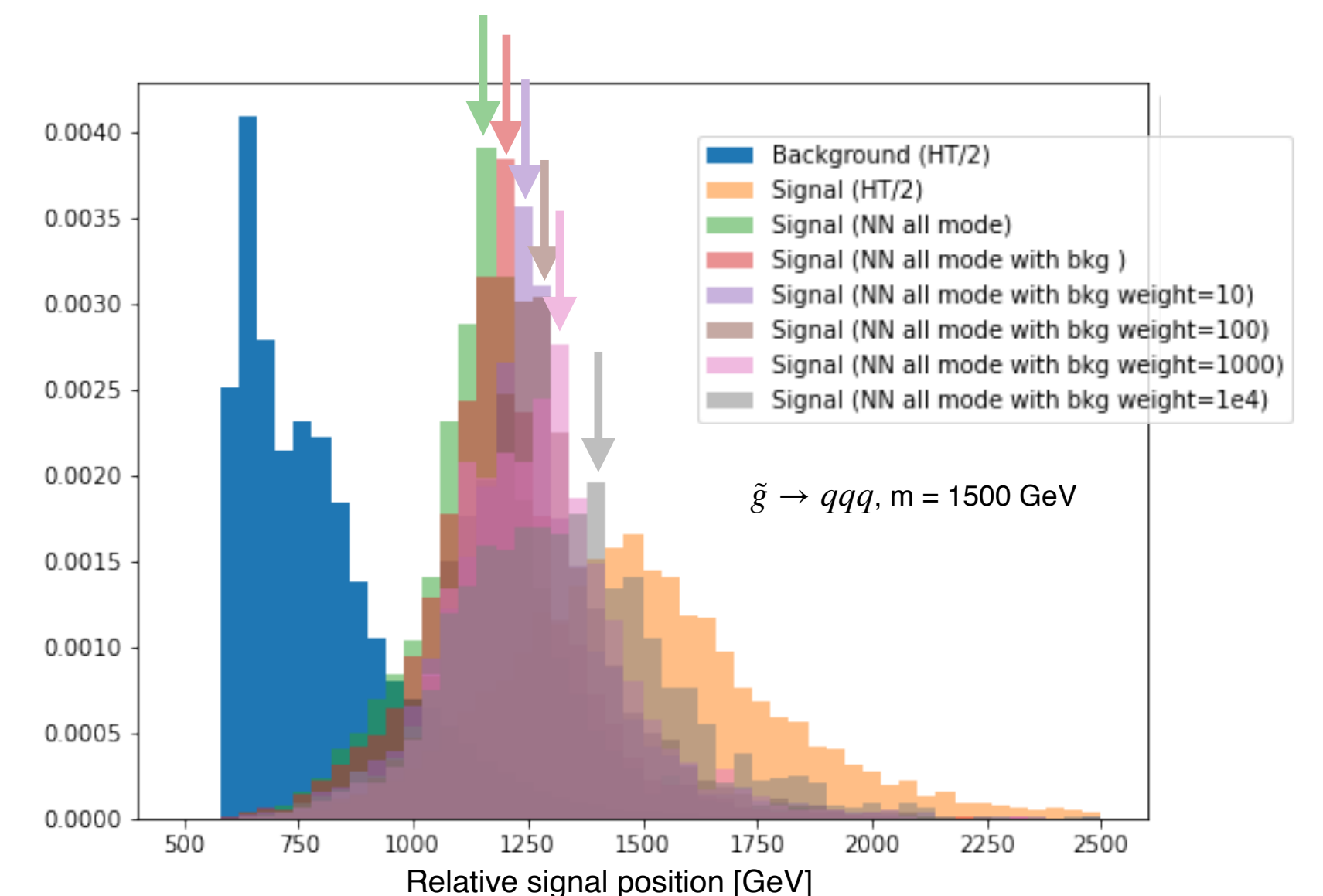
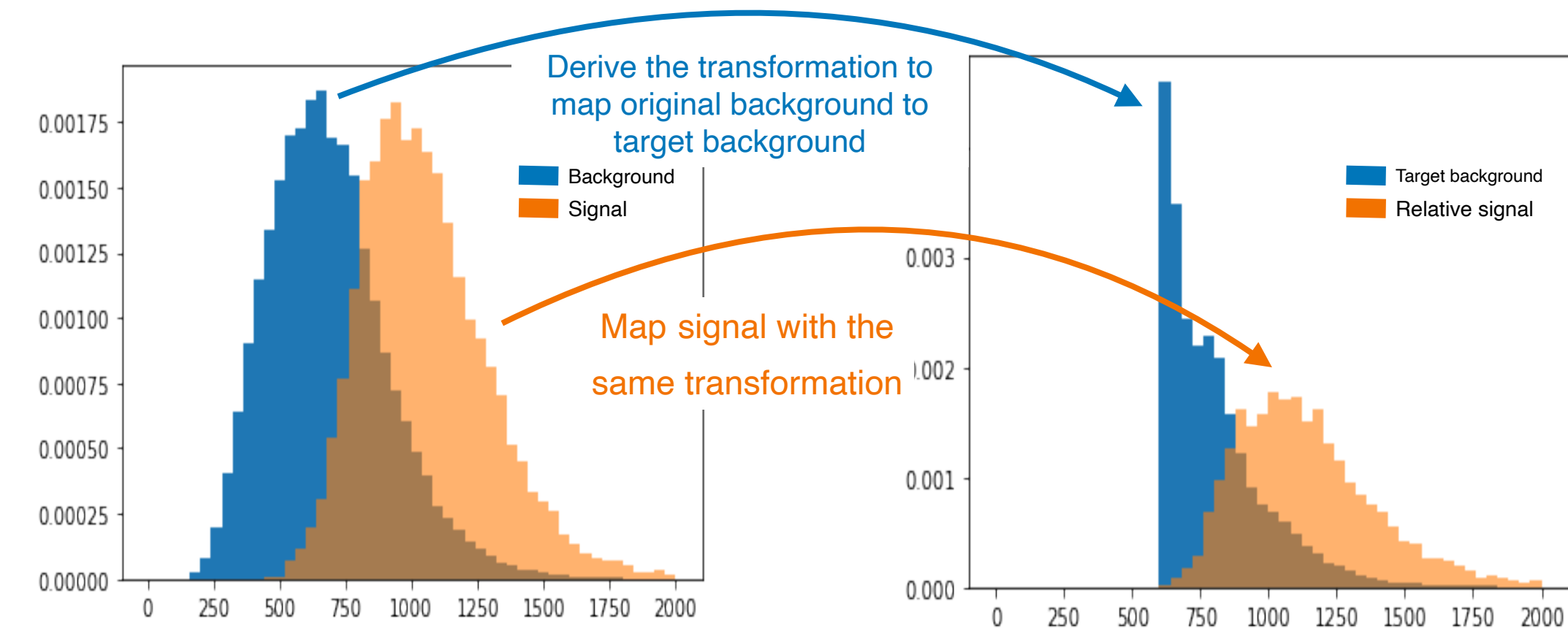
▶ Relative signal position

- Aim to compare signal shape on the same background distribution

▶ Adding backgrounds to training samples with training weights

- Relative signal position goes to the right side as the background weight increases
- Increasing backgrounds' importance in the training effectively improves the background sculpting

Concept of relative signal position



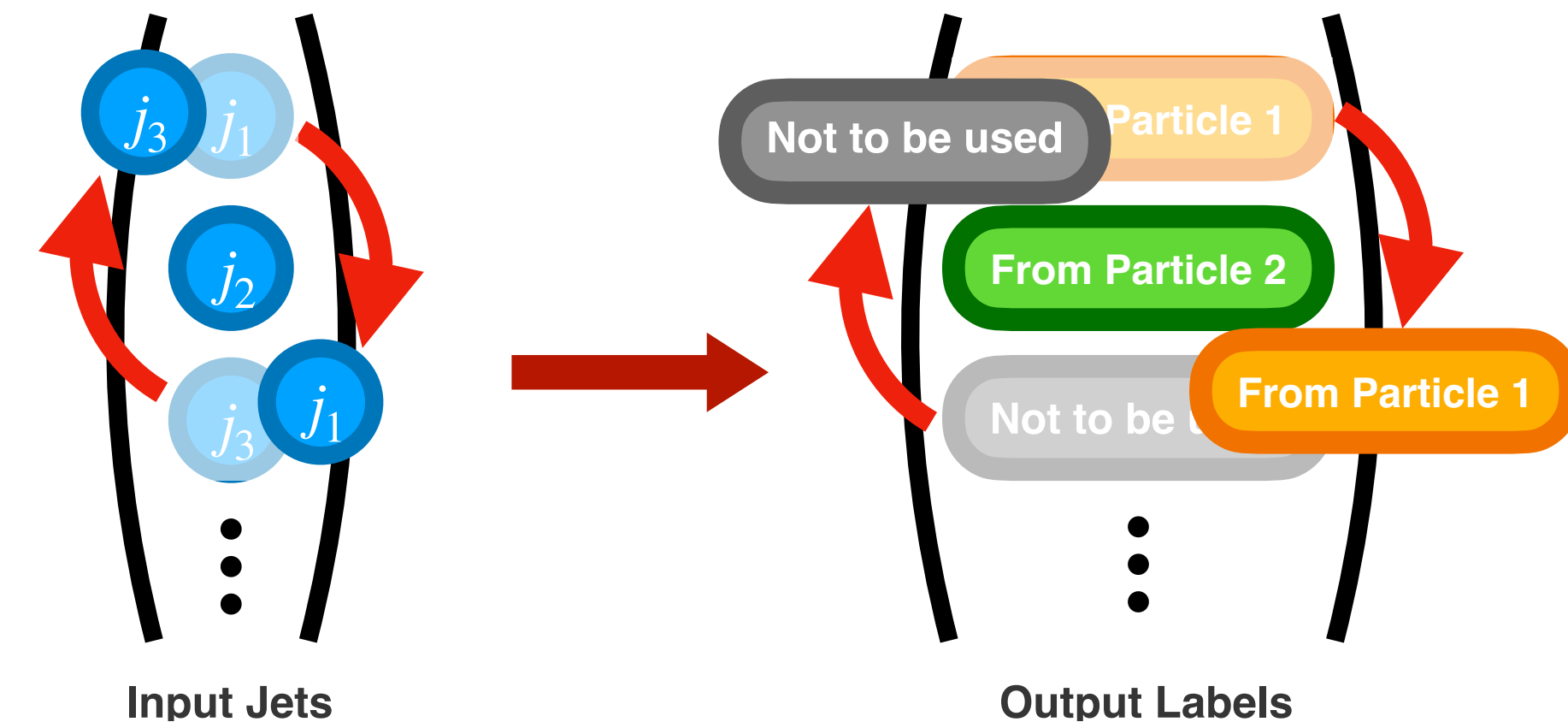
Training sample dependence: number of jets dependence

▶ Number of jets dependence

- Number of jets differs based on decay mode
- When an event doesn't have enough jets, last parts of the input are masked
- **NN learns not to use trailing jets in the reconstruction**

▶ Permutation equivariance

- Jet grouping should not depend on jets' order
 - When swap two jets, the output label should be swapped too
- Permutation equivariant linear transformation can be constructed with per-jet transformation + pooling
- Replace all dense layer with permutation equivariant layer
- **Permutation equivariant (and cannot learn jet order) by structure**



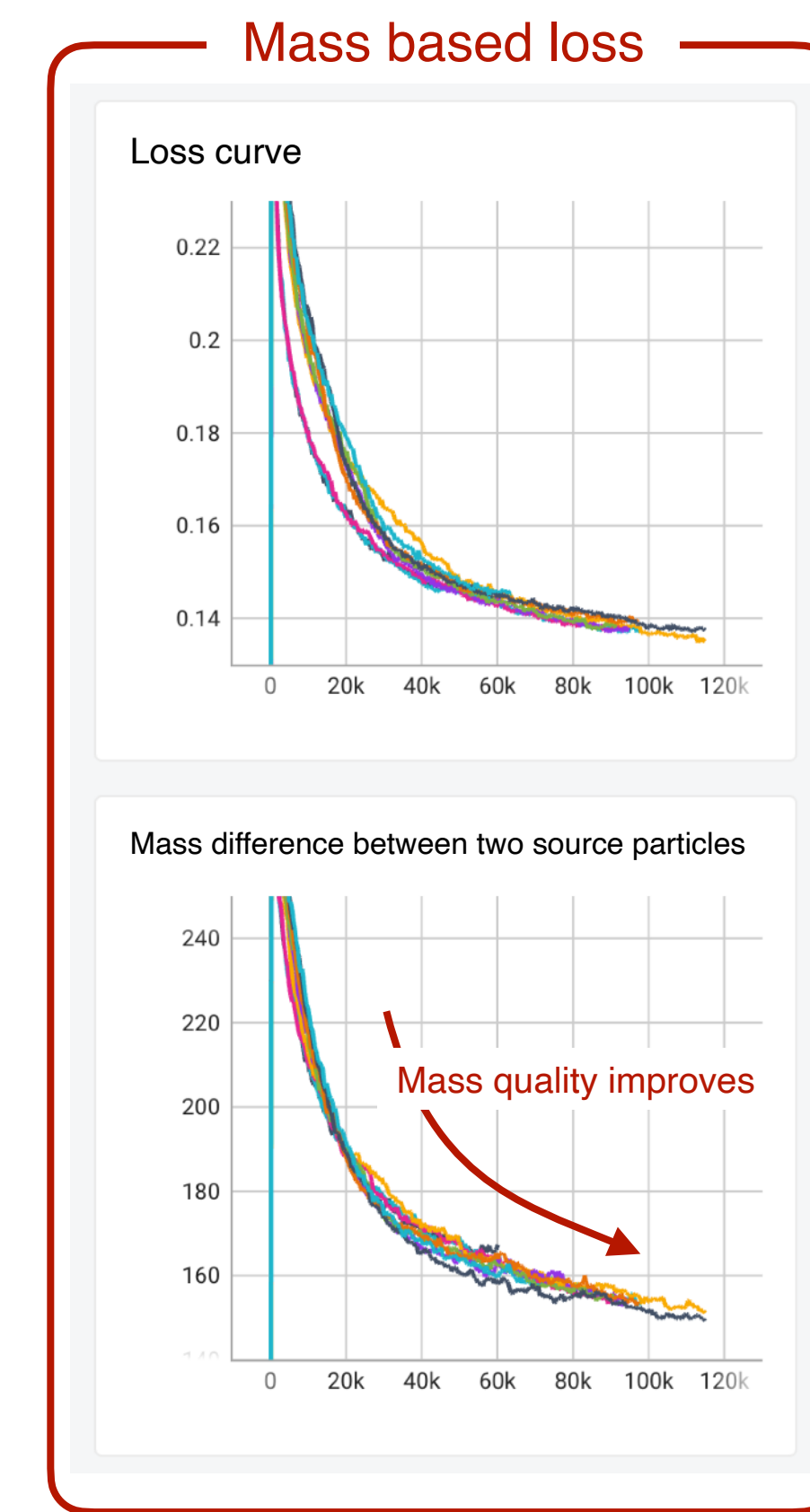
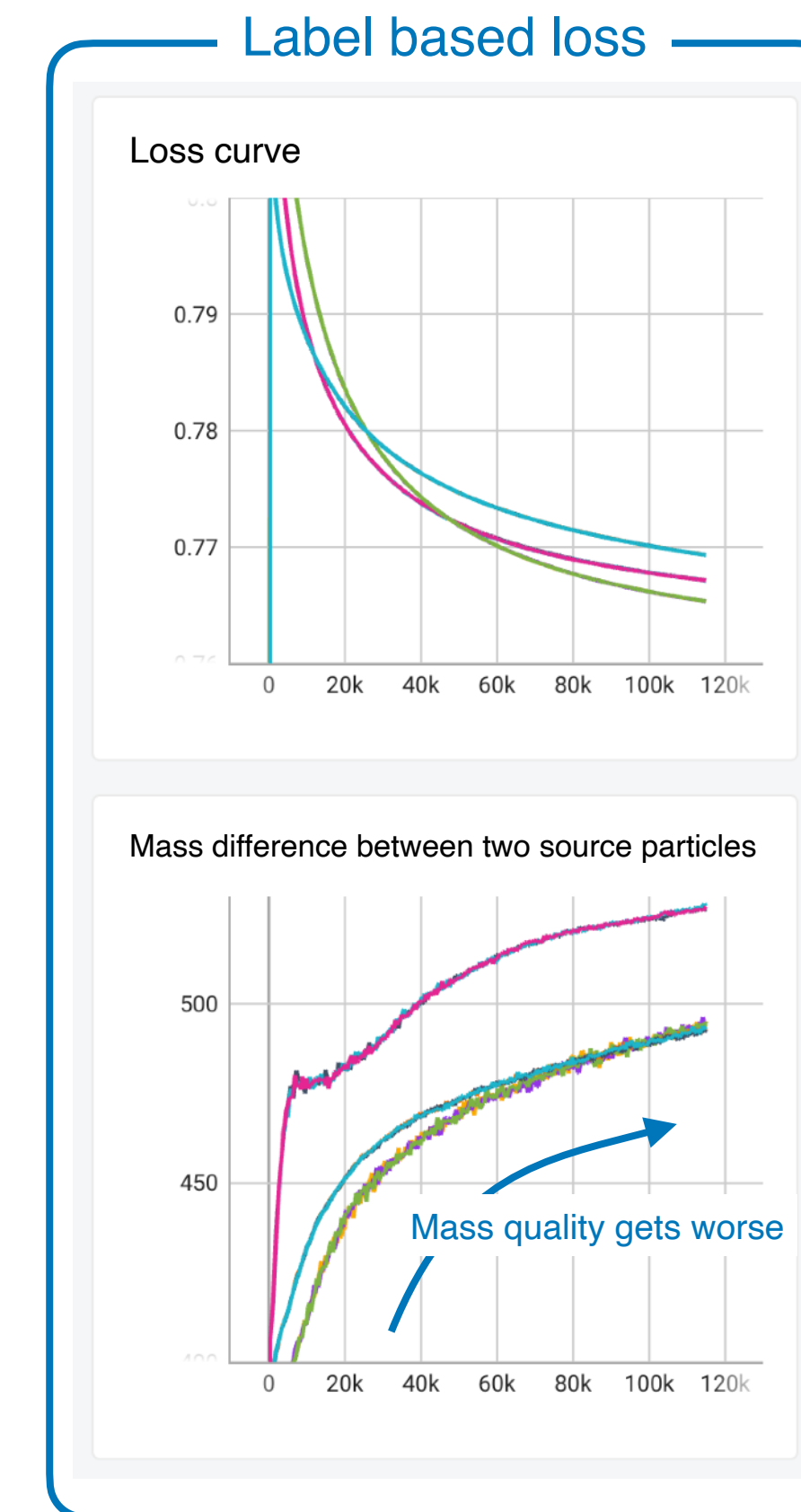
Loss function definition

► Loss function

- Output of the NN: 3-category label × 12 jets
- **Label based loss**
 - Focus on labeling accuracy: Cross-entropy loss
- **Mass based loss**
 - Focus on the difference between reconstructed mass and true mass
 - Utilize **Gumbel-softmax function** for differentiable reconstruction

► **Label based v.s. mass based**

- Labeling accuracy → **label based** works better
- Reconstructed mass quality
 - **Mass based** works better
 - With **label based**, mass quality gets worse as the loss decreases (the training progresses)



Result - reconstruction characteristics

► Characteristics evaluation

- Evaluate two aspects: background sculpting(AUC) and peak quality
- Reconstruct signals which is not known in the training

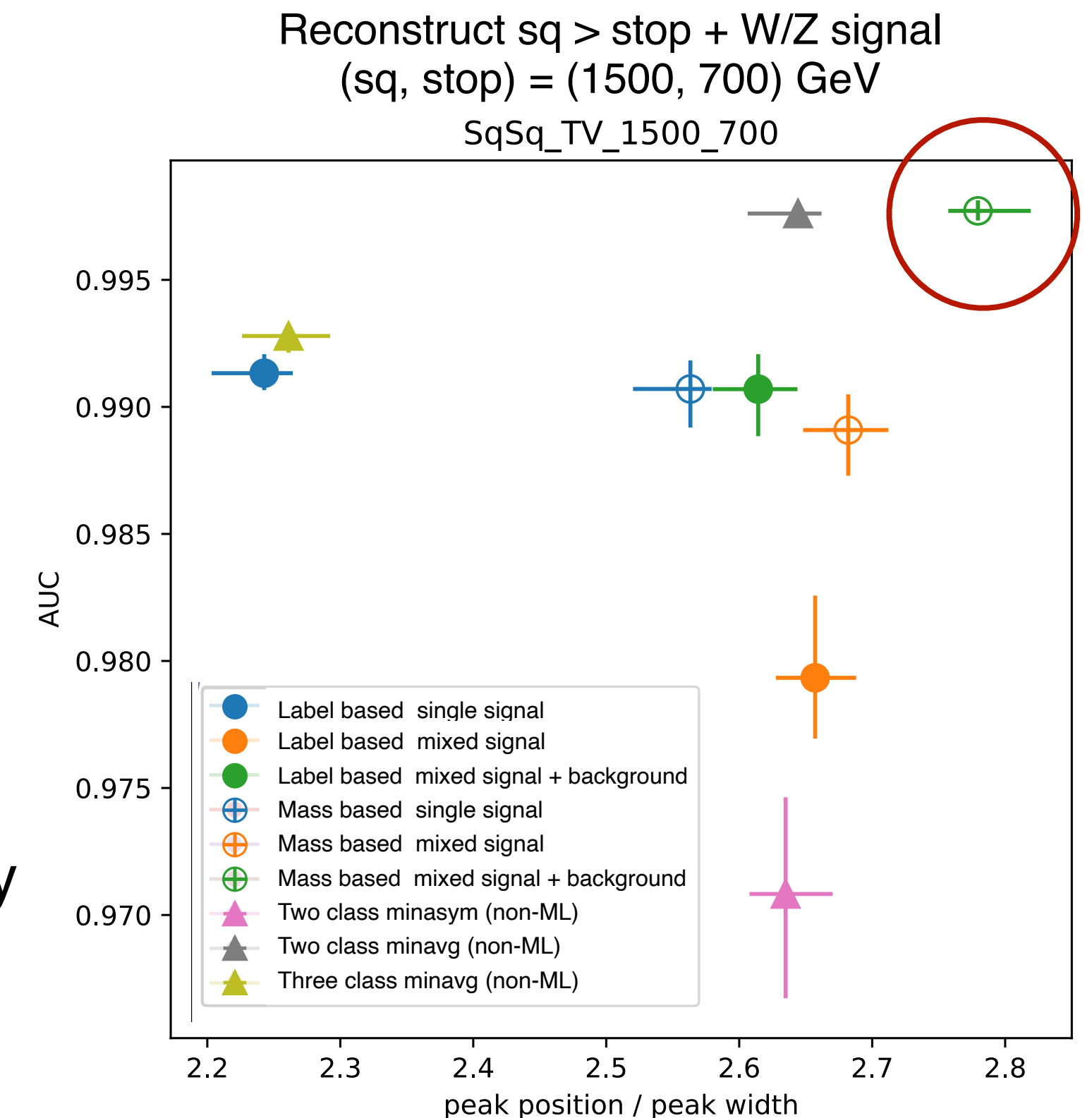
► Compare different settings, including non-ML method

- Six different ML setting
 - Two losses: label based loss, mass based loss
 - Three sample composition: single signal, mixed signal, signals + background
- Three non-ML method

► Result

- Label based (filled circle) v.s. mass based (empty circles)
-> Mass based outperforms in both aspects, bkg sculpting and peak quality
- Single signal v.s. mixed signal v.s. signal+background
 - We can see the effects
 - Mixing different signals enhances peak quality
 - Adding background mitigates background sculpting

► Mass based with signal+background outperforms all



Summary / future challenges

► Summary

- **Bump hunt with weakly supervised ML**
 - **Need narrow mass peak as well as model-independence**
- **Model-independence in ML based reconstruction**
 - Although it is simple, **training sample adjustment** helps a lot
 - Mass dependence, background sculpting, decay mode dependence
 - For the dependence which cannot be dealt with sample adjustment, modify architecture
- **Mass based loss improves the performance compared to cross-entropy loss**

► Challenges

- How to check model-independence systematically?
 - Currently, exclude one decay mode from the training and test the performance on it
 - Can we use ML to evaluate generalness of the method?
 - Some sort of anomaly detection on “functions’ behavior”...?

Backup