



# Analysis of Flavor Models by Diffusion Model

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Soon to be submitted [arXiv:2503.xxxxx]



# Machine Learning ( $\subset$ AI)

- A technique in which a computer extracts hidden rules or patterns as it iteratively learns data.

Supervised Learning



Reinforcement Learning

- S. Nishimura, C. Miyao, H. Otsuka,  
• JHEP12(2023)021 (2304.14176 [hep-ph])  
• 2409.10023 [hep-ph]

Unsupervised Learning

- K. Ishiguro, S. Nishimura, H. Otsuka,  
• JHEP08(2024)133 (2312.07181 [hep-th])

2025/02/18-21

KEK-PH 2025 winter

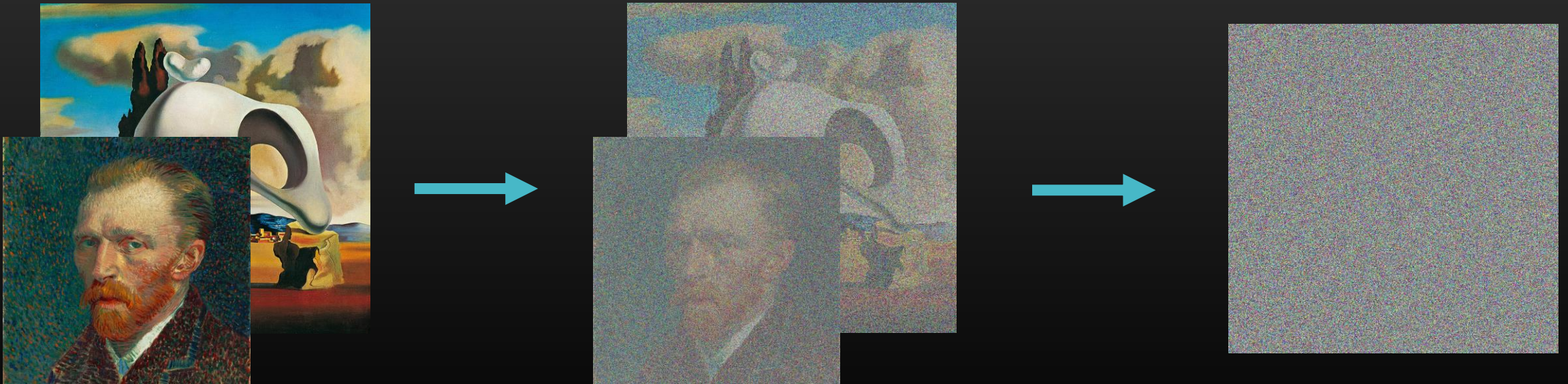
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# Diffusion Model (DM)

- A type of generative AI, which is used in image generation.  
Ex) AI services “Stable Diffusion” & “DALL-E in ChatGPT”
- Diffusion process : Adding noises to data
- Reverse process : Remove noises from Gaussian noise

# Diffusion Model (DM)

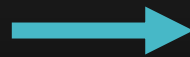
- **Diffusion process** : Initial pictures are added noises until they become pure Gaussian noises.



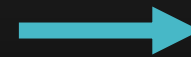
# Diffusion Model (DM)

- **Reverse process** : Pictures are generated by denoising.

Ex) Make an image with a touch of Salvador Dalí.



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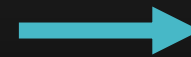
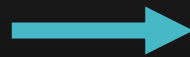
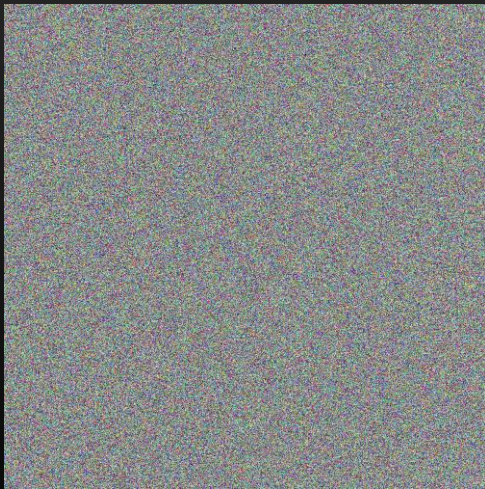
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# Diffusion Model (DM)

- Conditional DM : Pictures are generated with conditional labels.

Ex) Make an image of “**The Persistence of Memory**” by Salvador Dalí,

**with a touch of Van Gogh.**



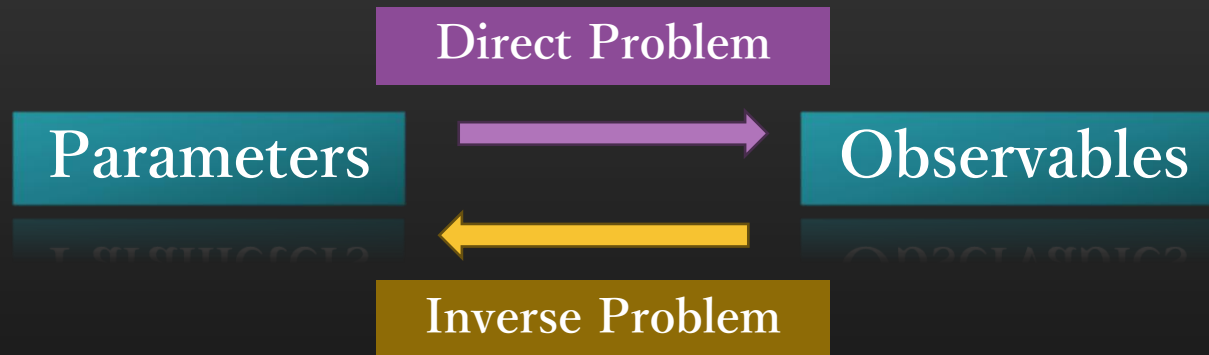
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6

# Key Point

- Using the diffusion model, we analyze  $S'_4$  modular flavor model.



- We found various parameters as an inverse problem, and show the  $S'_4$  model occurs spontaneous CP violation.

# The Standard Model (SM)

- SM describes the behavior of elementary particles with a high degree of accuracy. It is valid for  $\sim 10^{-18}$  m. However, there are many problems. (neutrino masses, generation, ……)
- The search for new physics beyond the Standard Model (BSM) is the challenge in particle physics.



# Flavor Physics

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graph TD; A[Flavor Physics] --- B[Mass Hierarchy]; A --- C[Flavor Mixing];
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Mass Hierarchy

Flavor Mixing

# Modular Flavor Model ( 1 )

- Modular flavor symmetry can explain the hierarchical structure of the quarks & the leptons.  
Ex)  $SL(2, Z)$ ,  $\Gamma_2 \simeq S_3$  (symmetric group of degree 3) ,  
 $S'_4$  (double covering of  $S_4$ )
- Yukawa couplings are representation of modular symmetry.  
These depend on moduli  $\tau$  remaining as a degree of freedom.

# Modular Flavor Model ( 2 )

Y.Abe, T.Higaki, J.Kawamura, T.Kobayashi

Phys.Lett.B 842 (2023) 137977

- Superpotential of  $S'_4$  modular flavor model

$$W = H_u \left\{ \sum_{a=1}^2 \alpha_a \left( Q Y_3^{(k_{ua}+k_Q)} \right)_1 u_a^c + \alpha_3 \left( Q Y_{\hat{3}}^{(k_{u3}+k_Q)} u_3^c \right)_1 \right\} \\ + H_d \sum_{i=1}^3 \left\{ \beta_i \left( Q Y_3^{(k_{di}+k_Q)} d_i^c \right)_1 \right\}$$

- Under modular transformation, modular form with weight  $k$  is defined as a function such that  $f_i(\gamma\tau) = (c\tau + d)^k \rho_{ij}(\gamma) f_j(\tau)$ .

$Y_3^k$  means 3 representation with weight  $k$ .

# Modular Flavor Model ( 3 )

- When representations and weights are fixed,  
Yukawa couplings are calculated using modular forms.

$$Y_u = \begin{pmatrix} \alpha_1 \left[ Y_3^{k_{u1}+k_Q}(\tau) \right]_1 & \alpha_2 \left[ Y_3^{k_{u2}+k_Q}(\tau) \right]_1 & \alpha_3 \left[ Y_{\widehat{3}}^{k_{u3}+k_Q}(\tau) \right]_1 \\ \alpha_1 \left[ Y_3^{k_{u1}+k_Q}(\tau) \right]_3 & \alpha_2 \left[ Y_3^{k_{u2}+k_Q}(\tau) \right]_3 & \alpha_3 \left[ Y_{\widehat{3}}^{k_{u3}+k_Q}(\tau) \right]_3 \\ \alpha_1 \left[ Y_3^{k_{u1}+k_Q}(\tau) \right]_2 & \alpha_2 \left[ Y_3^{k_{u2}+k_Q}(\tau) \right]_2 & \alpha_3 \left[ Y_{\widehat{3}}^{k_{u3}+k_Q}(\tau) \right]_2 \end{pmatrix}$$

- To reproduce masses and mixings of the quarks,  
 $O(1)$  constants  $\alpha, \beta$  and moduli  $\tau$  should be determined properly.

# Motivation

- Diffusion model is known as “Generative AI”  
(generate new data and information based on learning)
- It may be possible to
  - generate unknown parameters that reproduce the flavor structure in an observable-driven way (Inverse problem)
  - consider a wide range of parameters without limiting the search space (in contrast to conventional methods)

# Procedure of Learning

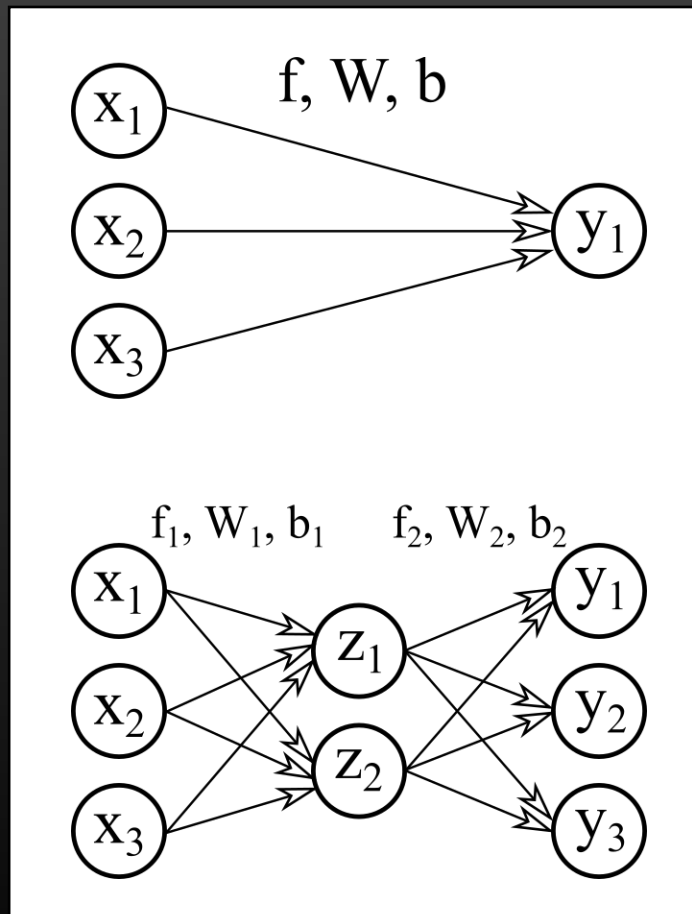
- Generating parameters  $G = \{\tau, \alpha, \beta\}$  ( $\alpha, \beta$  are real)

Calculated observables as labels  $L = \left\{ \frac{m_u}{m_t}, \frac{m_c}{m_t}, \frac{m_d}{m_b}, \frac{m_s}{m_b}, |U_{ij}^{\text{CKM}}|, J^q \right\}$

For various time step  $t$ ,

- 1)  $G$  is prepared randomly, and related label  $L$  is calculated
- 2) A random fluctuation  $\Delta G$  (noise) is added as  $G_t = \frac{T-t}{T} G + \frac{t}{T} \Delta G$
- 3) A neural network is trained to predict  $\Delta G$  from  $G_t$  &  $L$

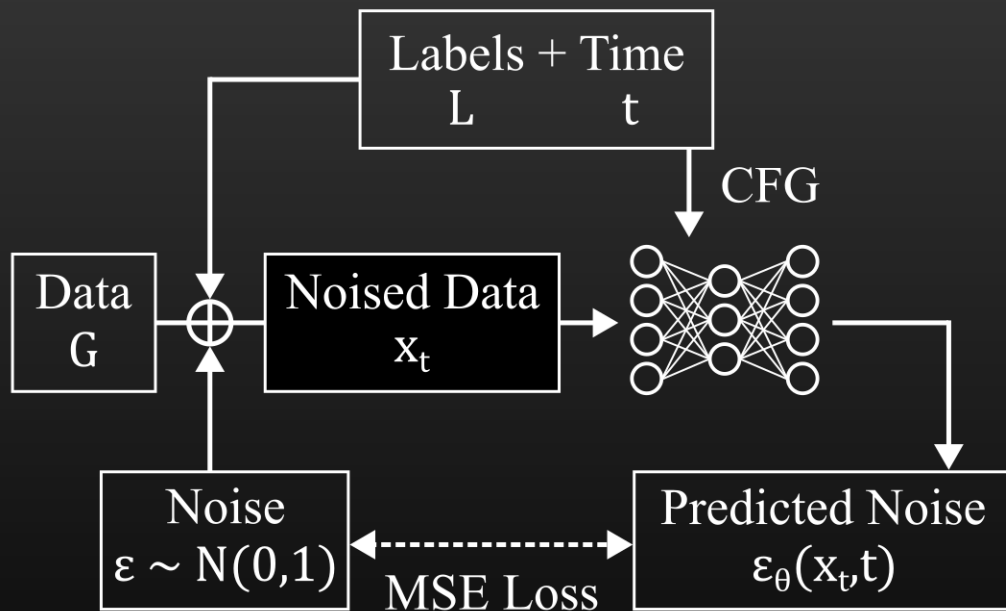
# Neural Network ( 1 )



- The mathematical model of brains.  
It has input layers ( $x$ ) & output layers ( $y$ ).
- Outputs are calculated from the inputs using parameters  $W, b$  (weight & bias) activation function  $f$

$$y_1 = f(W_1x_1 + W_2x_2 + W_3x_3 + b)$$

# Neural Network ( 2 )



- In the diffusion model,
  - input : noised data & label info
  - output : predicted noise
- Weight  $W$  & bias  $b$  are updated to decrease the difference between added noise and predicted noise.



# Example of Learning ( 1 )

1)  $G$  is prepared randomly, and related label  $L$  is calculated

$$G: \{\tau, \alpha, \beta\} = \{1 + 2i, 3, 4\} \rightarrow L: \left\{ \frac{m_u}{m_t}, \frac{m_c}{m_t} \right\} = \{10^{-2}, 10^{-1}\}$$

2) A random fluctuation  $\Delta G$  (noise) is added

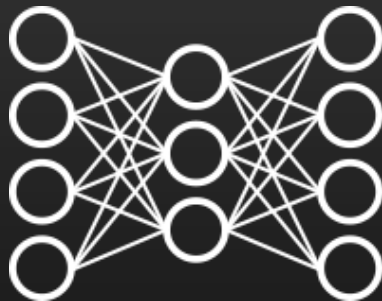
$$\Delta G: \{0.8 - 0.6i, -0.4, 0.2\} \rightarrow G_t: \frac{G + \Delta G}{2} = \{0.9 + 0.7i, 1.3, 2.1\}$$

# Example of Learning ( 2 )

3) A neural network is trained to predict  $\Delta G$  from  $G_t$  &  $L$

$$G_t: \{0.9 + 0.7i, 1.3, 2.1\}$$

$$L: \{10^{-2}, 10^{-1}\}$$



$$\Delta G_{\text{NN}}: \{0.7 + 0.1i, -0.2, 0.1\}$$



update parameters of NN  
to minimize the difference

$$\Delta G: \{0.8 - 0.6i, -0.4, 0.2\}$$

# Procedure of Generating

- Generating parameters  $G = \{\tau, \alpha, \beta\}$

Physical observables as labels  $L_{\text{exp}} = \left\{ \frac{m_u}{m_t}, \frac{m_c}{m_t}, \frac{m_d}{m_b}, \frac{m_s}{m_b}, |U_{ij}^{\text{CKM}}|, J^q \right\}$

- 1) Pure noise  $G_T$  is prepared from Gaussian distribution
- 2) A predicted fluctuation  $\Delta G$  is denoised as  $G_t = \frac{T-t}{T} G_{t+1} - \frac{t}{T} \Delta G$
- 3) New data  $G_0$  is generated along experimental label  $L_{\text{exp}}$

# Example of Generating ( 1 )

- We adopted real values of observables during generating.

$$L_{\text{exp}}: \left\{ \frac{m_u}{m_t}, \frac{m_c}{m_t} \right\} = \{5.4 \times 10^{-6}, 2.8 \times 10^{-3}\}$$

1 ) Pure noise  $G_T$  is prepared from Gaussian distribution

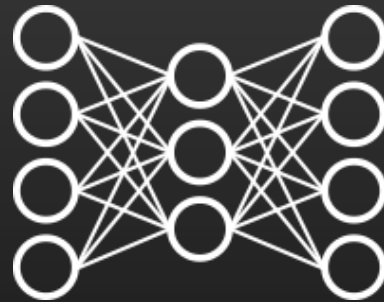
$$G_T: \{-0.3 + 0.7i, -1.2, 0.5\} \quad \text{from} \quad N(0,1)$$

# Example of Generating ( 2 )

2) A predicted fluctuation  $\Delta G$  is denoised

$G_T$ :

$$\{-0.3 + 0.7i, -1.2, 0.5\}$$



$\Delta G$ :

$$\{0.08 - 0.02i, -0.06, 0.1\}$$

$$G_{T-1}: \frac{G_T - \Delta G}{2} = \{-0.19 + 0.36i, -0.57, 0.20\}$$

3) New data  $G_0$  is generated along experimental label  $L_{\text{exp}}$

# Progress of **Generating** ( 1 )

- From the parameters found by DM, 14 observables are calculated.

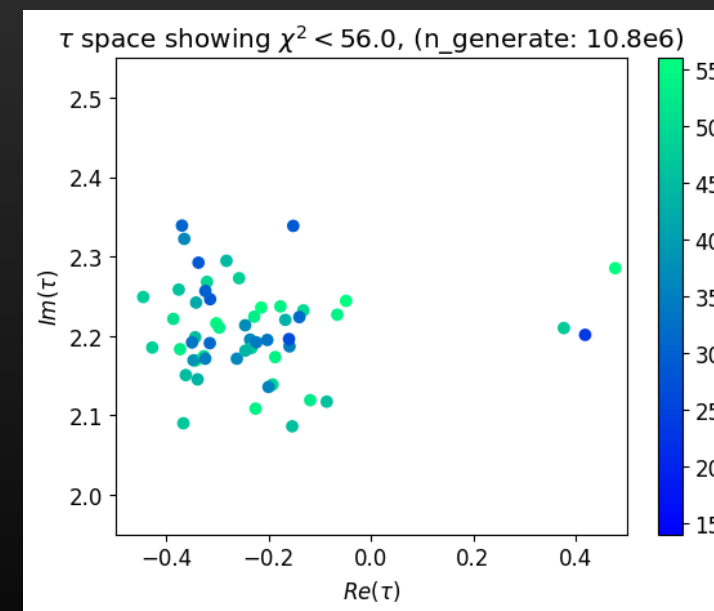
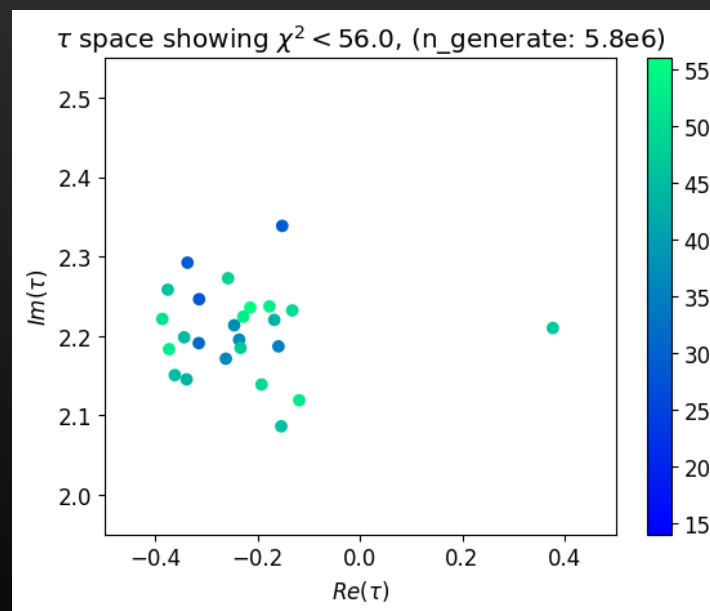
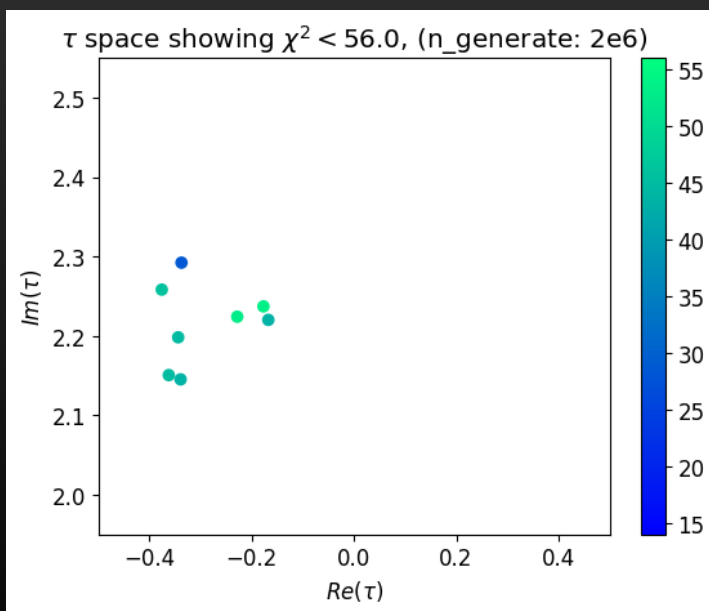
$$\left\{ \frac{m_u}{m_t}, \frac{m_c}{m_t}, \frac{m_d}{m_b}, \frac{m_s}{m_b}, |U_{ij}^{\text{CKM}}|, J^q \right\}$$

- $\chi^2$  is defined from calculated & experimental values  $v_{\text{cal}}, v_{\text{exp}}$

$$\chi^2 = \sum \chi_i^2 = \sum \frac{(v_{i,\text{cal}} - v_{i,\text{exp}})^2}{v_{i,\text{error}}^2}$$

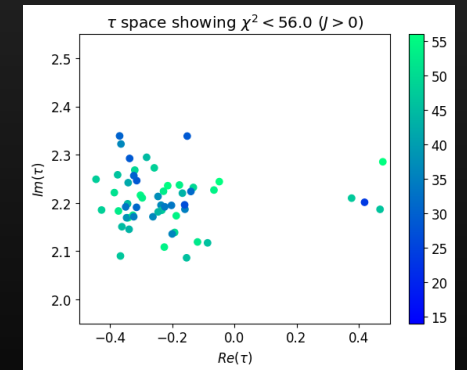
# Progress of Generating ( 2 )

- The distributions of moduli  $\tau$  with high accuracy are shown.  
(with an increase in the data generated by the DM)



# Result : Various Solutions

- The flavor structure of  $S'_4$  model is sensitive to  $\text{Im } \tau$ . It is an arduous task to find good parameter regions. Analytically, large  $\text{Im } \tau$  is preferred. (Ex :  $\text{Im } \tau = 2.8$ )
- We found various solutions with smaller  $\text{Im } \tau \sim 2.2$  even without strict limitations for param. region.



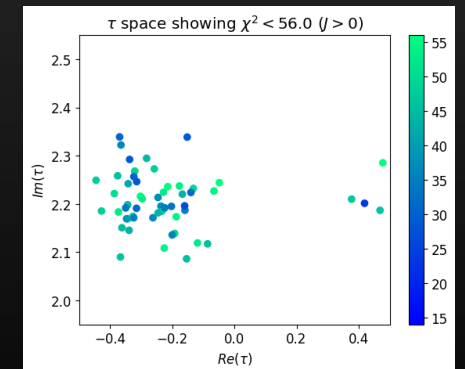


# Result : Spontaneous CP Violation

- Coefficients  $\alpha, \beta$  are real. We found  $\text{Re } \tau$  reproduces Jarlskog invariant, so spontaneous CP violation is derived.

$$J_{\text{DM}} \sim 2.70 \times 10^{-5}, \quad J_{\text{exp}} = 2.87 \times 10^{-5}$$

- In previous works, complex coefficients are often introduced to reproduce CP violation. It is interesting to find the parameters with SCPV.

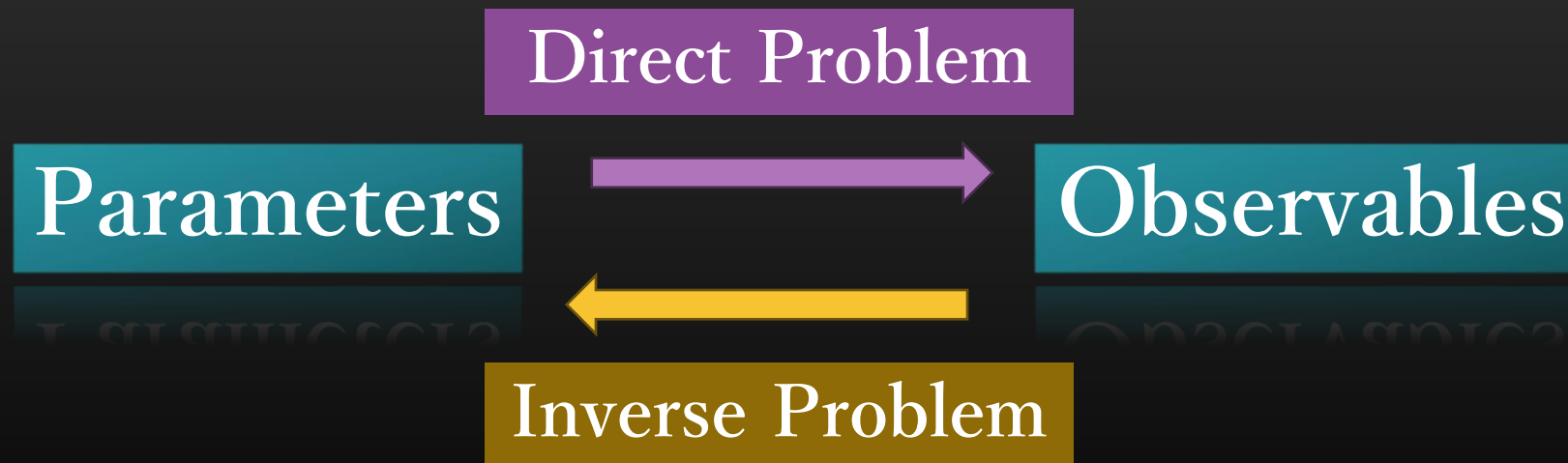


# Summary : application of **DM** for flavor physics

- We focused on the  $S'_4$  modular flavor model, and searched parameters with diffusion model.
- We found various parameters with smaller  $\text{Im } \tau$  which reproduce the flavor structure of quark sector in an observable-driven way. This approach do not need constraints on searching region.

# Summary : application of **DM** for flavor physics

- Even when coefficients of Yukawa are real, the  $S'_4$  model occurs the spontaneous CP violation.



# Outlook

- Will spontaneous CP violation be visible with  $A_4$  or other modular symmetries? Will non-trivial parameters be discovered?
- We hope to construct a framework that get predictions from flavor models by simply specifying the experimental values.

