

On the bias renormalization in the cosmological perturbation theory

Takahiko Matsubara
KEK

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KEK-Cosmo AY2024@KEK

Conventional bias expansion

- For illustration, let's consider the simplest case
 - Local-In-Matter-Density (LIMD) bias
 - Neglect gravitational evolution (i.e., bias in Lagrangian space)

$$\delta_g = b_1 \delta_R + \frac{b_2}{2!} (\delta_R^2 - \sigma_R^2) + \frac{b_3}{3!} \delta_R^3 + \frac{b_4}{4!} (\delta_R^4 - \sigma_R^4) + \dots$$

- where

$$\delta_R(\mathbf{x}) = \int \frac{d^3 k}{(2\pi)^3} e^{i\mathbf{k}\cdot\mathbf{x}} \delta_L(\mathbf{k}) W(kR)$$

$$\sigma_R^2 = \langle \delta_R^2 \rangle = \int \frac{k^2 dk}{2\pi^2} P_L(k) W^2(kR)$$

b_n 's are the bare bias parameters

Conventional renormalization of bias

- Bias renormalization in conventional PT (orig., McDonald 2006)
 - Straightforward calculation of the correlation function (Assuming Gaussian stats):

$$\begin{aligned}\xi_g(r) &= \langle \delta_g(\mathbf{x}_1) \delta_g(\mathbf{x}_2) \rangle \\ &= (b_1^2 + b_1 b_3 \sigma_R^2 + \dots) \xi_R(r) + \frac{1}{2} (b_2^2 + b_2 b_4 \sigma_R^2 + \dots) \xi_R^2(r) + \dots\end{aligned}$$

- Defining renormalized bias parameters

$$\tilde{b}_1 \equiv b_1 + \frac{b_3 \sigma_R^2}{2} + \dots, \quad \tilde{b}_2 \equiv b_2 + \frac{b_4 \sigma_R^2}{2} + \dots, \dots$$

- We have

$$\xi_g(r) = \tilde{b}_1^2 \xi_R(r) + \frac{\tilde{b}_2^2}{2} \xi_R^2(r) + \dots$$

Statistically renormalized bias parameters

- Instead of the conventional procedure above, the renormalized bias parameters are equivalently defined statistically without renormalizing order-by-order:

- I.e., define

$$\tilde{b}_n = \left\langle \frac{\partial^n \delta_g}{\partial \delta_R^n} \right\rangle$$

- This is the same as the renormalized bias parameters derived by conventional procedure. In fact, applying Taylor expansion

$$\delta_g = \sum_{n=1}^{\infty} \frac{b_n}{n!} \delta_R^n \quad \Rightarrow \quad \tilde{b}_n = \left\langle \frac{\partial^n \delta_g}{\partial \delta_R^n} \right\rangle = \sum_{m=0}^{\infty} \frac{b_{2m+n} \sigma_R^{2m}}{(2m-1)!!}$$

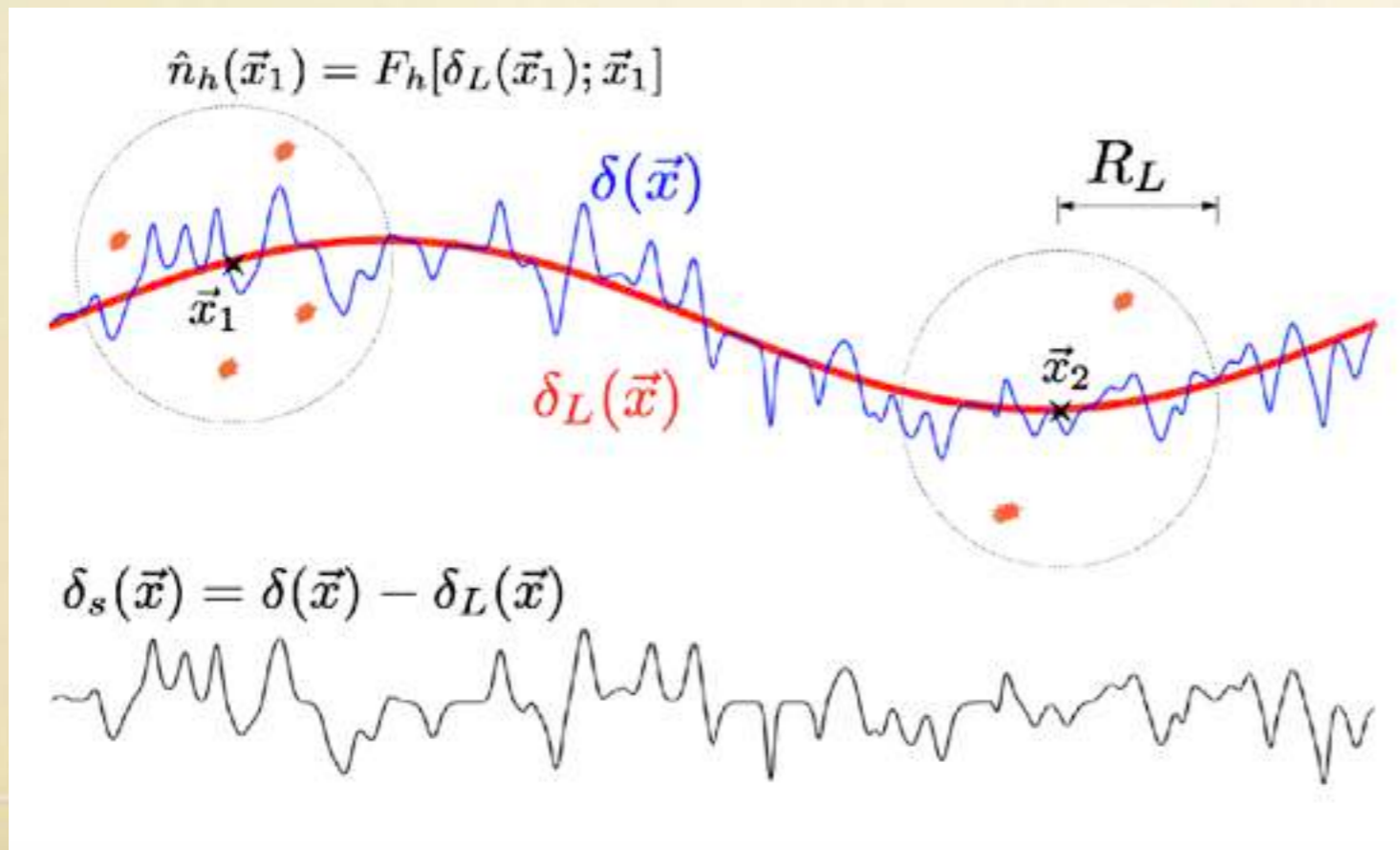
$$\langle \delta_R^p \rangle = (p-1)!! \sigma_R^2 \quad (\text{Assuming Gaussian stats})$$

- Exactly agree with the conventional renormalized parameters
- The above statistically defined parameters extend the concept of conventionally defined renormalized bias parameters
 - They do not have to be perturbative, i.e., no problem with non-perturbative bias such as Press-Schechter, Peaks, etc.
 - Works even in the case of non-Gaussian stats

Relation to the Separate Universe approach

- The renormalized bias parameters are closely related to the Peak-Background Split method in the Separate Universe approach (Schmidt, Jeong and Desjacques 2013)
 - In the LIMD model,

$$b_n = \frac{\bar{\rho}^n}{\bar{\rho}_g} \frac{\partial^n \bar{\rho}_g}{\partial \bar{\rho}^n} \iff b_n = \left\langle \frac{\partial^n \delta_g}{\partial \delta_R^n} \right\rangle$$



$$\bar{\rho} \rightarrow \bar{\rho}' = \bar{\rho}(1 + \delta_R),$$

$$\bar{\rho}_g \rightarrow \bar{\rho}'_g = \bar{\rho}_g(1 + \delta_g)$$

Renormalized bias functions

- The renormalized bias parameters => Renormalized bias functions

- One can consider more general situations: the biased field is a functional (instead of a function) of the linear density field
- In this way, any conceivable (generally nonlocal) bias models can be considered
- The renormalized bias functions are defined by the statistical average of functional derivatives (in Lagrangian space)

$$c_g^{(n)}(\mathbf{k}_1, \dots, \mathbf{k}_n) \equiv \left\langle \frac{\delta^n \delta_g^L}{\delta \delta_L(\mathbf{k}_1) \cdots \delta \delta_L(\mathbf{k}_n)} \right\rangle$$

- Ex. LIMD model =>

- $$c_g^{(n)}(\mathbf{k}_1, \dots, \mathbf{k}_n) = W(k_1 R) \cdots W(k_n R) \left\langle \frac{\partial^n \delta_g^L}{\partial \delta_R^n} \right\rangle = W(k_1 R) \cdots W(k_n R) \tilde{b}_g^L$$

The integrated perturbation theory (iPT)

- The integrated perturbation theory (iPT)
 - Matsubara 2011, PRD 83, 083518
 - The gravitational evolutions are treated perturbatively (using Lagrangian perturbation theory)
 - But the bias is non-perturbatively included from the beginning, using the concept of renormalized bias functions
 - As a result, bias is NOT expanded into perturbative series
 - In particular, bias models with singular functions, such as Press-Schechter (with step function) and Peaks (with delta function), can be properly calculated in the framework of PT

Summary (on the bias renormalization)

- Statistically defined bias parameters (or bias functions) do NOT require conventional order-by-order renormalization
 - bias parameters NOT defined at the field level, but only statistically defined
- Instead, they are renormalized from the first place (“renormalized” in the sense of conventional PT)

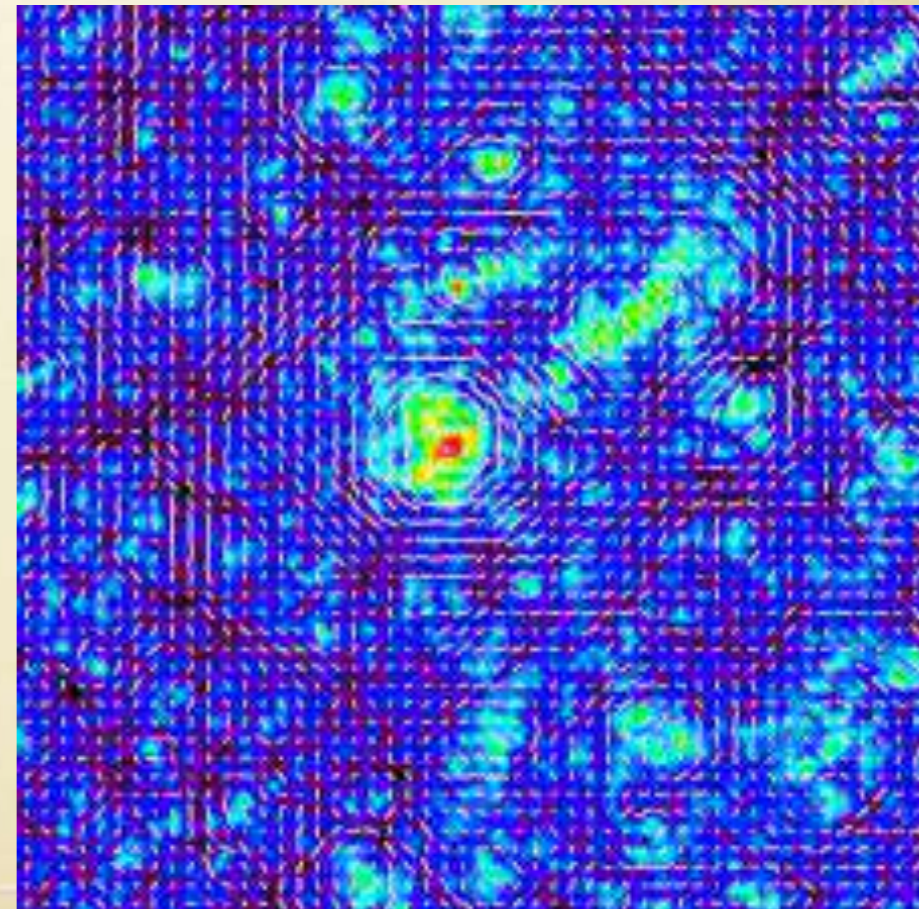
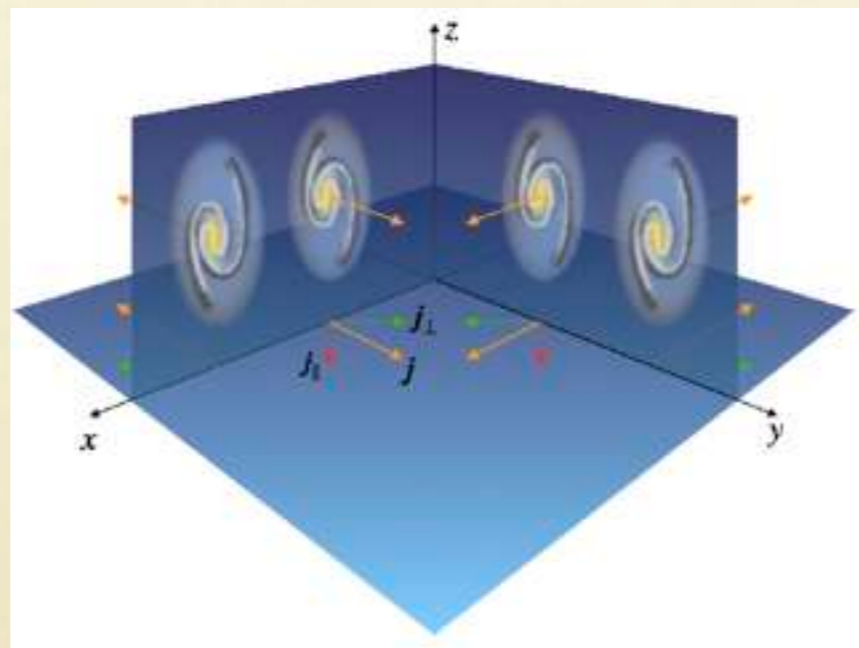
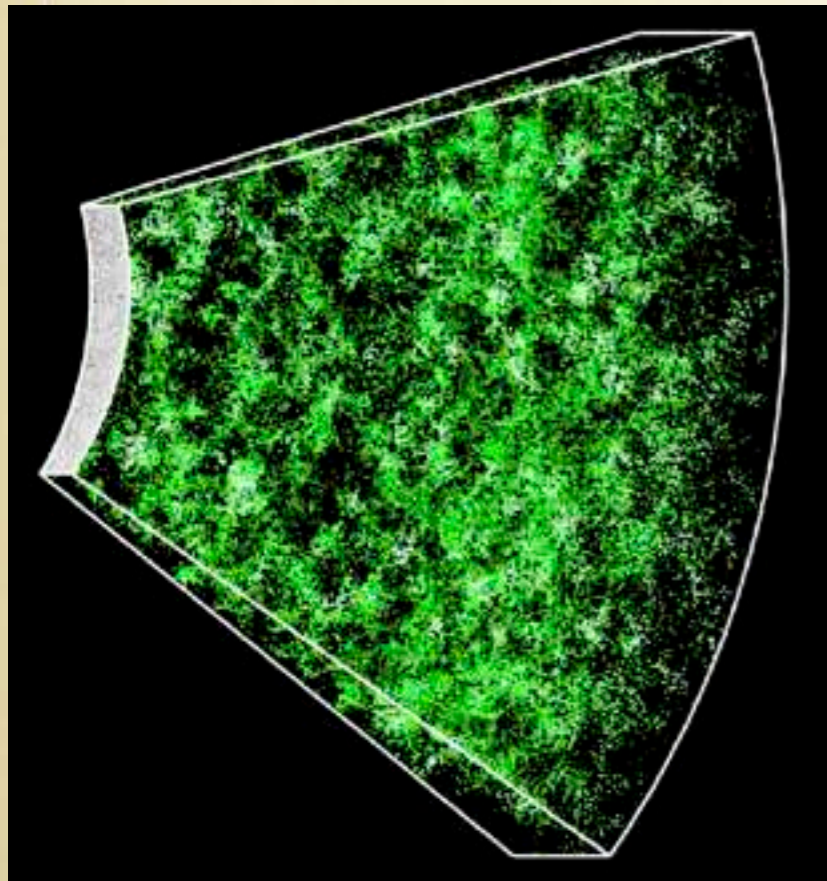
The integrated perturbation theory for cosmological tensor fields

Selected topics from:

- T. Matsubara, PRD 110, 063543 [arXiv:2210.10435] (Paper I)
- T. Matsubara, PRD 110, 063544 [arXiv:2210.11085] (Paper II)
- T. Matsubara, PRD 110, 063545 [arXiv:2304.13304] (Paper III)
- T. Matsubara, PRD 110, 063546 [arXiv:2405.09038] (Paper IV)

Tensor fields in cosmology

- Large-scale structure (LSS), weak lensing
 - galaxy density field: 3D rank-0 scalar field
 - galaxy angular momentum: 3D rank-1 vector field
 - galaxy shape field: 3D rank-2 (or higher) tensor fields

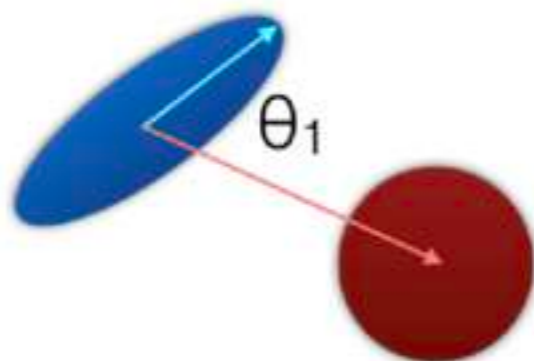


Example: galaxy shape alignment

- The spatial patterns of galaxy shapes:
 - The alignments are statistically correlated to the initial condition of the Universe, and thus to the large-scale structure of the universe

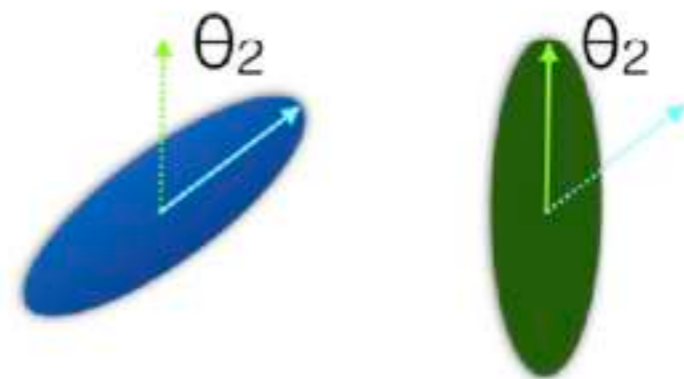
“Shape—position” alignment

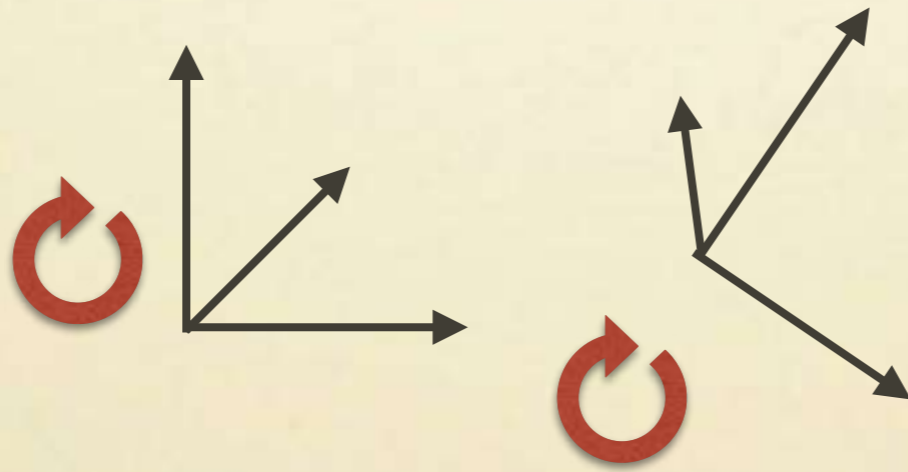
Neighbor can be of any mass/shape



“Shape—shape” alignment

Both galaxies must be prolate candidates





Moments of galaxy shapes

- Example of higher-rank tensor field
 - higher-order moments of galaxy shape

$$I_{i_1 \dots i_l}(\mathbf{x}) = \frac{\int d^3 x' (x'_{i_1} - x_{i_1}) \cdots (x'_{i_l} - x_{i_l}) \rho(\mathbf{x}')}{\int d^3 x' \rho(\mathbf{x}')}$$

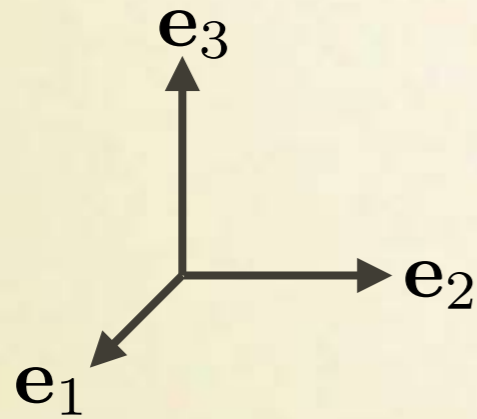
- The higher-order shape field

$$I_{i_1 \dots i_l}(\mathbf{x}) = \sum_{a \in \text{galaxies}} I_{i_1 \dots i_l}(\mathbf{x}_a) \delta_{\text{D}}^3(\mathbf{x} - \mathbf{x}_a)$$

- (Normalization is arbitrary)

Spherical basis

- Spherical basis in Cartesian coordinates



$$\mathbf{e}^0 \equiv \mathbf{e}_3, \quad \mathbf{e}^\pm \equiv \mp \frac{\mathbf{e}_1 \mp i\mathbf{e}_2}{\sqrt{2}}$$

- Traceless spherical tensor basis

$$\text{rank-0} : Y^{(0)} \equiv 1$$

$$\text{rank-1} : Y_i^{(0)} = e^0_i, \quad Y_i^{(\pm 1)} = e^\pm_i$$

$$\text{rank-2} : Y_{ij}^{(0)} = \sqrt{\frac{3}{2}} \left(e^0_i e^0_j - \frac{\delta_{ij}}{3} \right), \quad Y_{ij}^{(\pm 1)} = \sqrt{2} e^0_{(i} e^\pm_{j)}, \quad Y_{ij}^{(\pm 2)} = e^\pm_{(i} e^\pm_{j)}$$

...

$$\text{rank-}l : Y_{i_1 \dots i_l}^{(m)} = \dots \quad (m = 0, \pm 1, \dots, \pm l)$$

Decomposition of tensor into spherical basis

- Any symmetric tensor can be decomposed into traceless tensors

$$T_{i_1 i_2 \dots i_l} = T_{i_1 i_2 \dots i_l}^{(l)} + \frac{l(l-1)}{2(2l-1)} \delta_{(i_1 i_2} T_{i_3 \dots i_l)}^{(l-2)} + \dots$$

- Decomposition of traceless tensor field into spherical basis:

$$F_{X i_1 \dots i_l}^{(l)}(\mathbf{x}) = F_{X l m}(\mathbf{x}) Y_{i_1 \dots i_l}^{(m)}$$

Power spectrum of tensor field

- Definition of the power spectrum in Fourier space

$$\langle F_{X_1 l_1 m_1}(\mathbf{k}) F_{X_2 l_2 m_2}(\mathbf{k}') \rangle = (2\pi)^3 \delta_D^3(\mathbf{k} + \mathbf{k}') P_{X_1 X_2 m_1 m_2}^{(l_1 l_2)}(\mathbf{k})$$

- Statistical isotropy

- When the Universe is statistically isotropic, the power spectrum should be invariant under the coordinate rotation
- In this case, the power spectrum should take the following form,

$$P_{X_1 X_2 m_1 m_2}^{(l_1 l_2)}(\mathbf{k}) = \sum_l \underbrace{(l_1 \ l_2 \ l)_{m_1 m_2}}_{\text{3j-symbol}} \underbrace{C_{lm}(\hat{\mathbf{k}})}_{\text{Spherical harmonics (Racah's normalization)}} \underbrace{P_{X_1 X_2}^{l_1 l_2; l}(k)}_{\text{Invariant spectrum}}$$

Invariant spectrum

Symmetries of invariant spectrum

- Complex conjugate

$$P_{X_1 X_2}^{l_1 l_2; l*}(k) = P_{X_1 X_2}^{l_1 l_2; l}(k) \quad \text{i.e., real function}$$

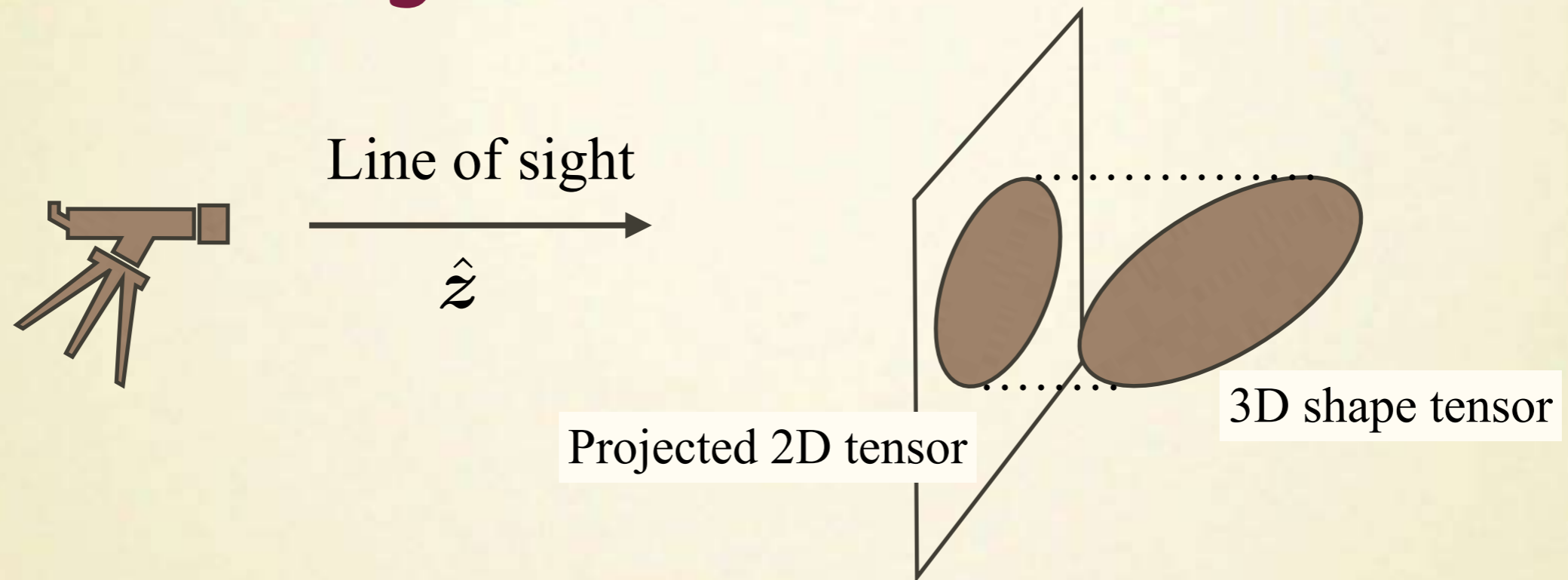
- Parity

$$P_{X_1 X_2}^{l_1 l_2; l}(k) \xrightarrow{\mathbb{P}} (-1)^{p_{X_1} + p_{X_2} + l_1 + l_2 + l} P_{X_1 X_2}^{l_1 l_2; l}(k)$$

- interchange

$$P_{X_2 X_1}^{l_2 l_1; l}(k) = (-1)^{l_1 + l_2} P_{X_1 X_2}^{l_1 l_2; l}(k)$$

Projection effects



- Measurable tensors in realistic observations
 - 2D projected tensor on the sky

$$f_{X i_1 \dots i_s}(\mathbf{x}) = \mathcal{P}_{i_1 j_1} \cdots \mathcal{P}_{i_s j_s} F_{X j_1 \dots j_s}(\mathbf{x})$$

$$\mathcal{P}_{ij} = \delta_{ij} - \hat{z}_i \hat{z}_j \quad (\text{projection tensor})$$

(distant-observer approximation applied)

2D irreducible decomposition

- 2D spherical basis

$$\mathbf{m}^{\pm} \equiv \mp \frac{\mathbf{e}_1 \mp i\mathbf{e}_2}{\sqrt{2}}$$

- Decomposition of 2D traceless tensor into 2D spherical basis

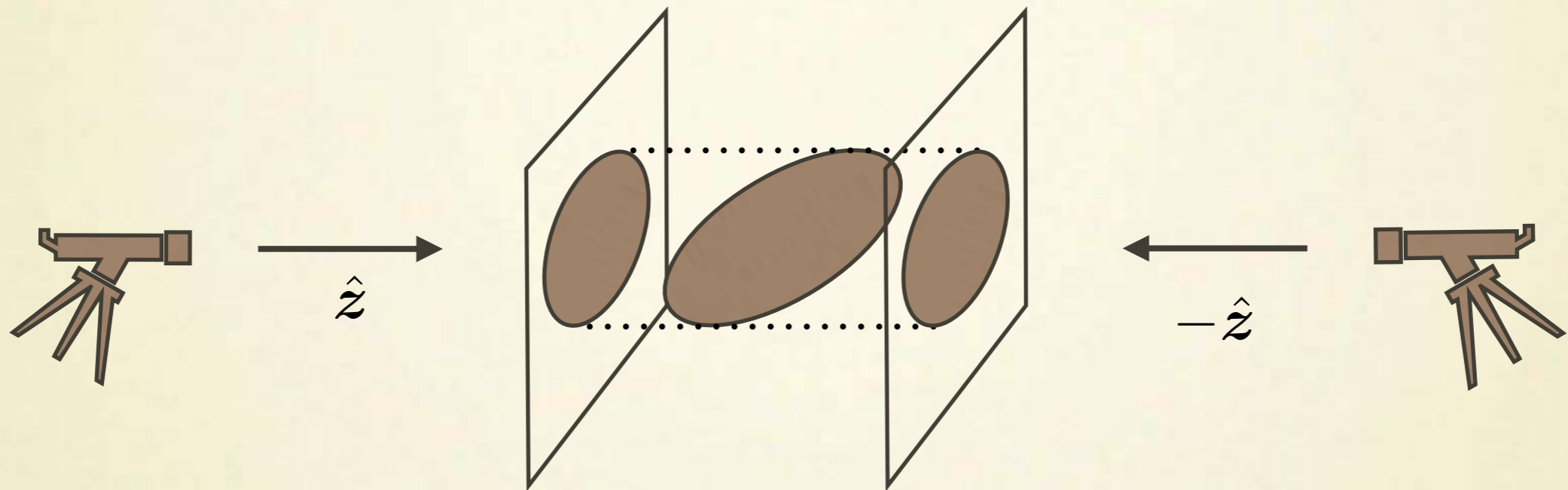
$$f_{X i_1 \dots i_s}^{(s)}(\mathbf{x}) = f_X^{(+s)}(\mathbf{x}) m_{i_1}^+ \dots m_{i_s}^+ + f_X^{(-s)}(\mathbf{x}) m_{i_1}^- \dots m_{i_s}^-$$

- Relation between 3D & 2D irreducible tensors

$$f_X^{(\pm s)}(\mathbf{x}) = i^s \sqrt{\frac{s!}{(2s-1)!}} \underbrace{F_{X s, \pm s}(\mathbf{x})}_{= F_{X l m}(\mathbf{x})|_{l=s, m=\pm s}}$$

- (The last eq. shows that the projected tensor from a 3D traceless tensor remains traceless also in the projected 2D space)

Flip symmetry of projected field



- Flip symmetry: invariance under $\hat{\mathbf{z}} \xrightarrow{\mathbb{F}} -\hat{\mathbf{z}}$

$$f_X^{(\pm s)}(\mathbf{x}) \xrightarrow{\mathbb{F}} f_X'^{(\pm s)}(\mathbf{x}) = e^{\pm 2is\phi} f_X^{(\mp s)}(-\mathbf{x}), \quad [\mathbf{x} : (x, \theta, \phi)]$$

- Parity+flip

$$f_X^{(\pm s)}(\mathbf{x}) \xrightarrow{\mathbb{PF}} f_X'^{(\pm s)}(\mathbf{x}) = (-1)^{p_X + s} e^{\pm 2is\phi} f_X^{(\mp s)}(\mathbf{x})$$

- Parity+flip in distant-observer limit is more similar to the “parity” in full-sky spherical coordinates

E/B decomposition of projected field

- In Fourier space,

$$f_X^{(\pm s)}(\mathbf{k}) = (\mp i)^s e^{\pm i s \phi} \left[f_X^{\text{E}(s)}(\mathbf{k}) \pm i f_X^{\text{B}(s)}(\mathbf{k}) \right]$$

- PF symmetry is simply given in the E/B modes

$$f_X^{\text{E}(s)}(\mathbf{k}) \xrightarrow{\text{PF}} (-1)^{p_X + s} f_X^{\text{E}(s)}(\mathbf{k})$$

$$f_X^{\text{B}(s)}(\mathbf{k}) \xrightarrow{\text{PF}} (-1)^{p_X + s + 1} f_X^{\text{B}(s)}(\mathbf{k})$$

- When $p_X + s = \text{even}$, E mode is parity even, B mode is parity odd
- When $p_X + s = \text{odd}$, E mode is parity odd, B mode is parity even

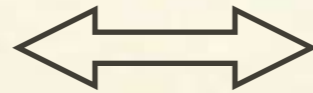
E/B decomposition



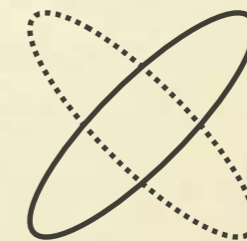
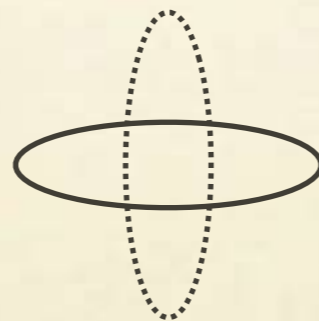
E mode

B mode

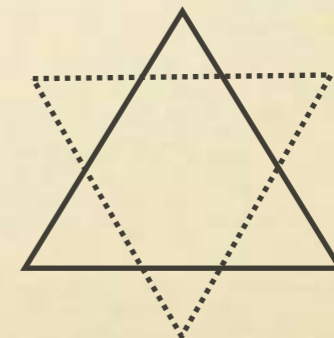
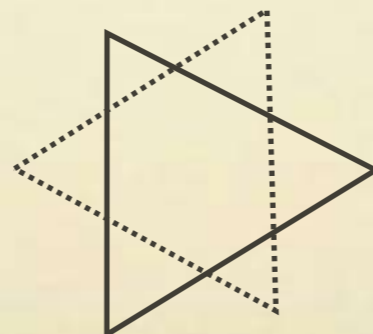
$s = 1$



$s = 2$

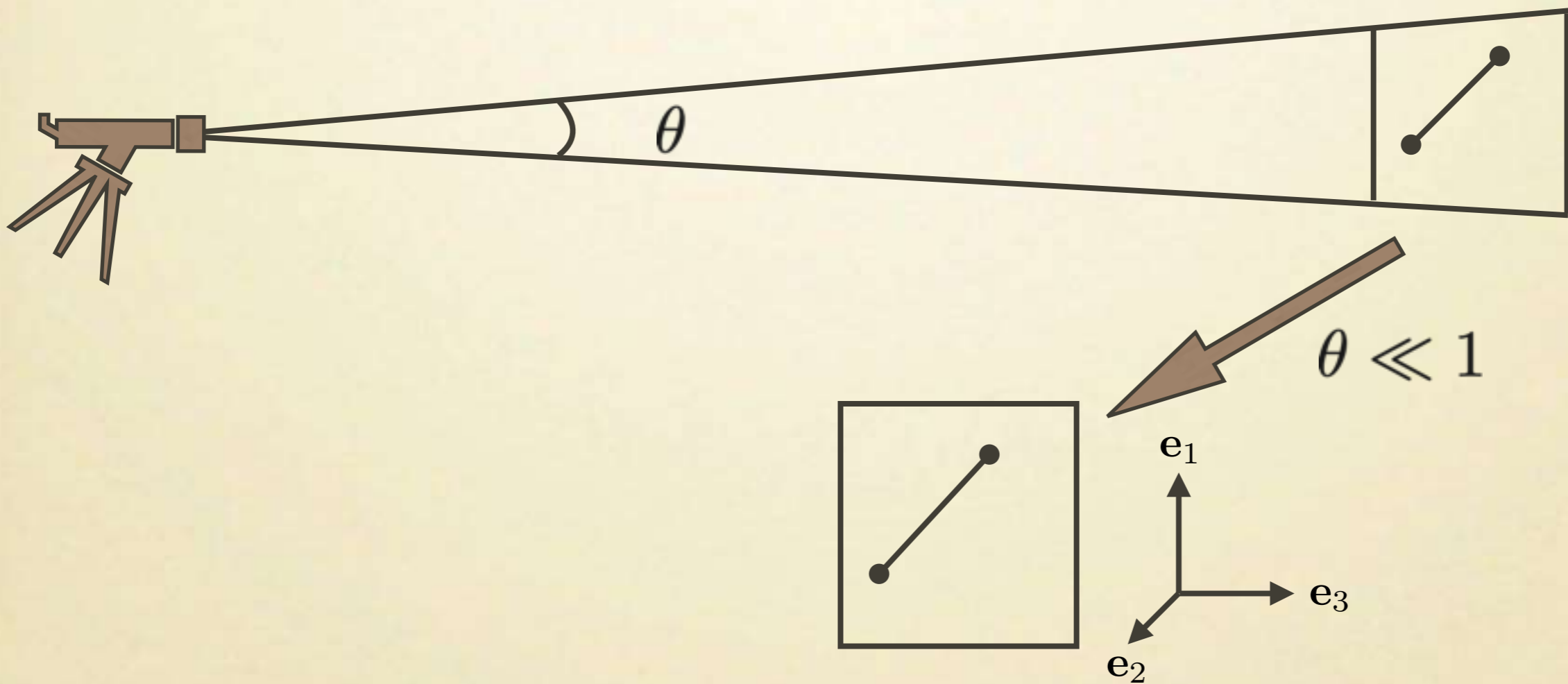


$s = 3$



Distant-observer approximation

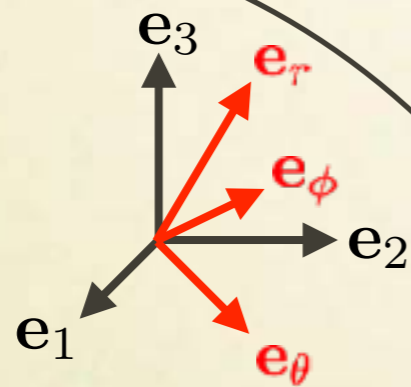
- DOA: clustering scales are much smaller than the distance to the objects



Spherical coordinates \rightarrow Cartesian Coordinates

Full-sky formulation: spherical coordinates

- Spherical basis in spherical coordinates

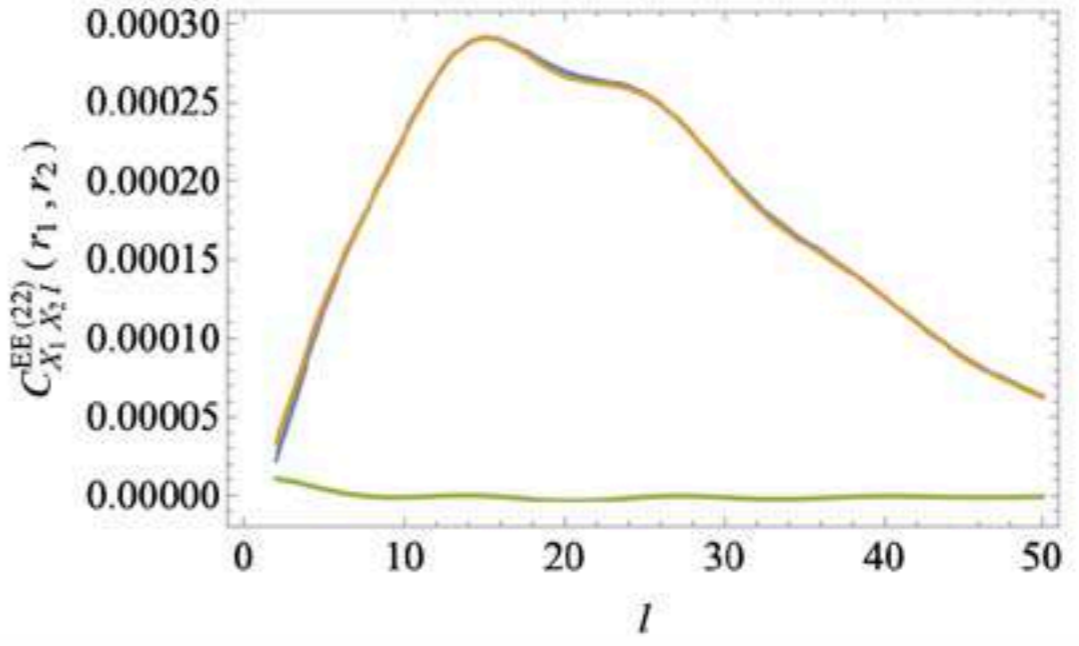
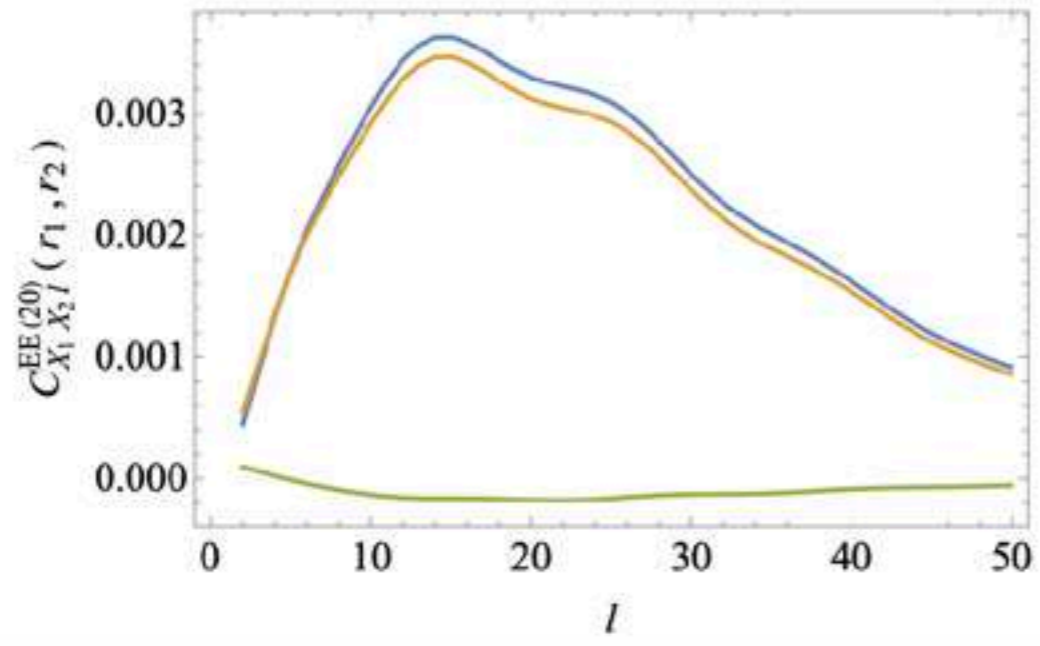
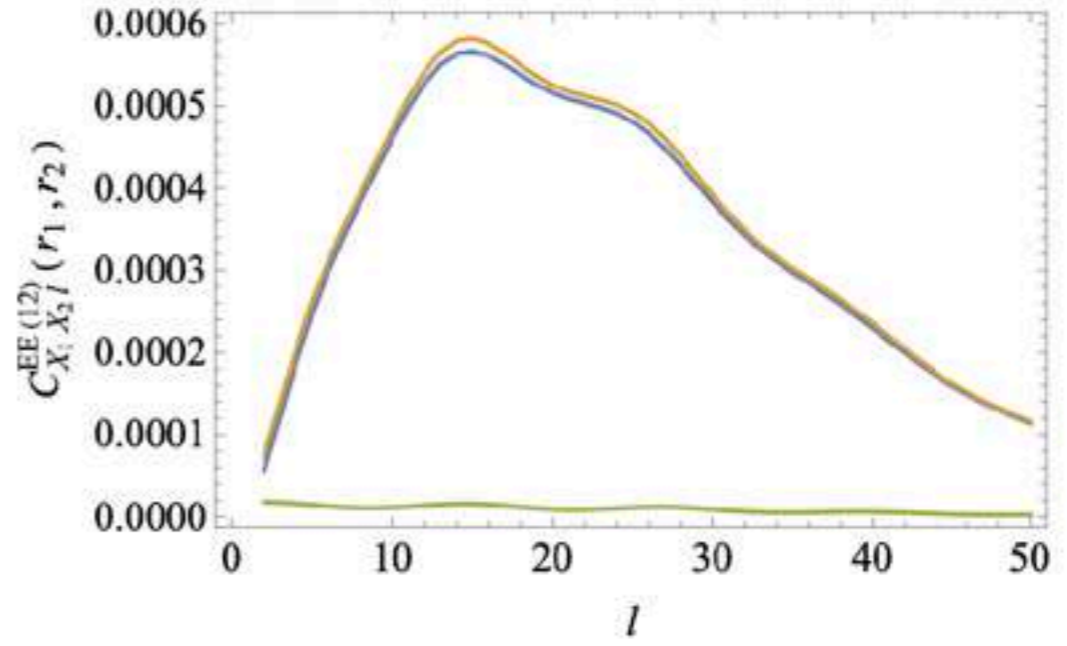
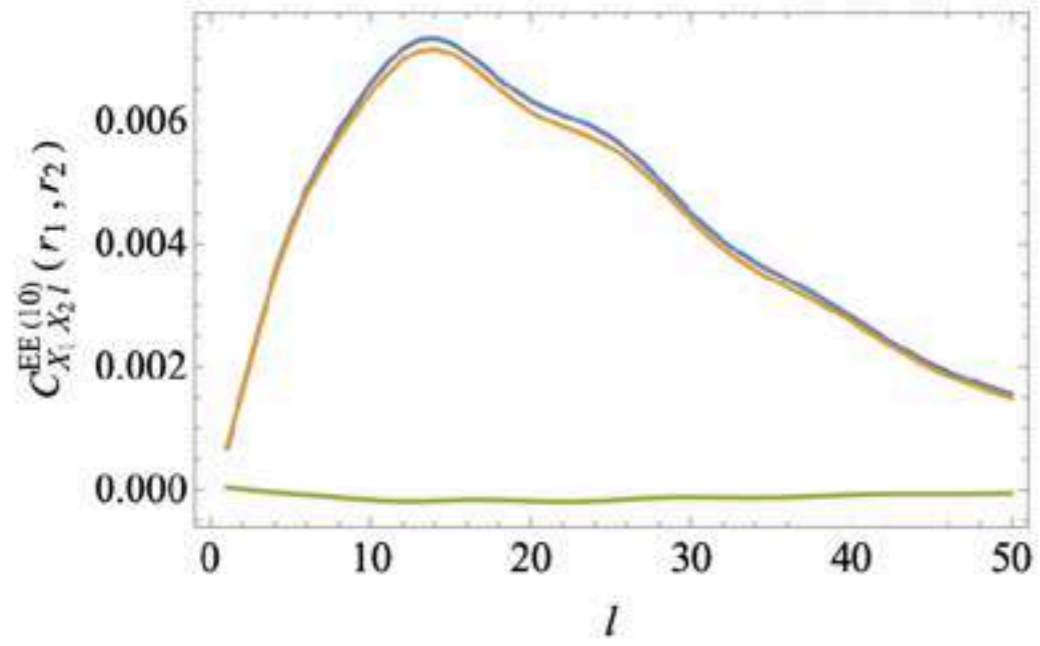
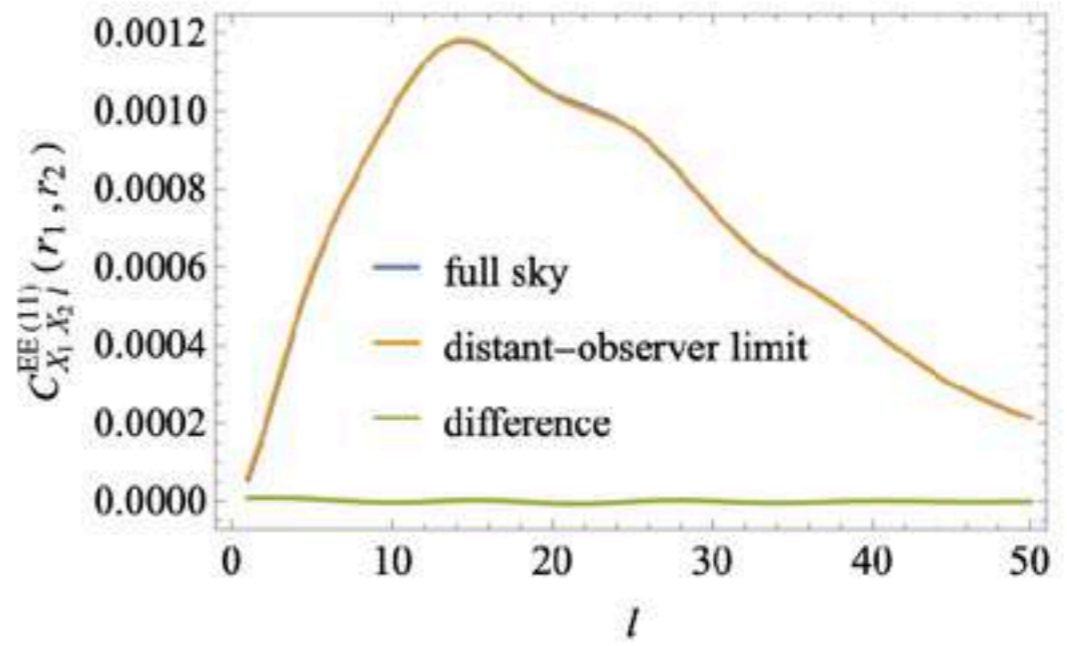
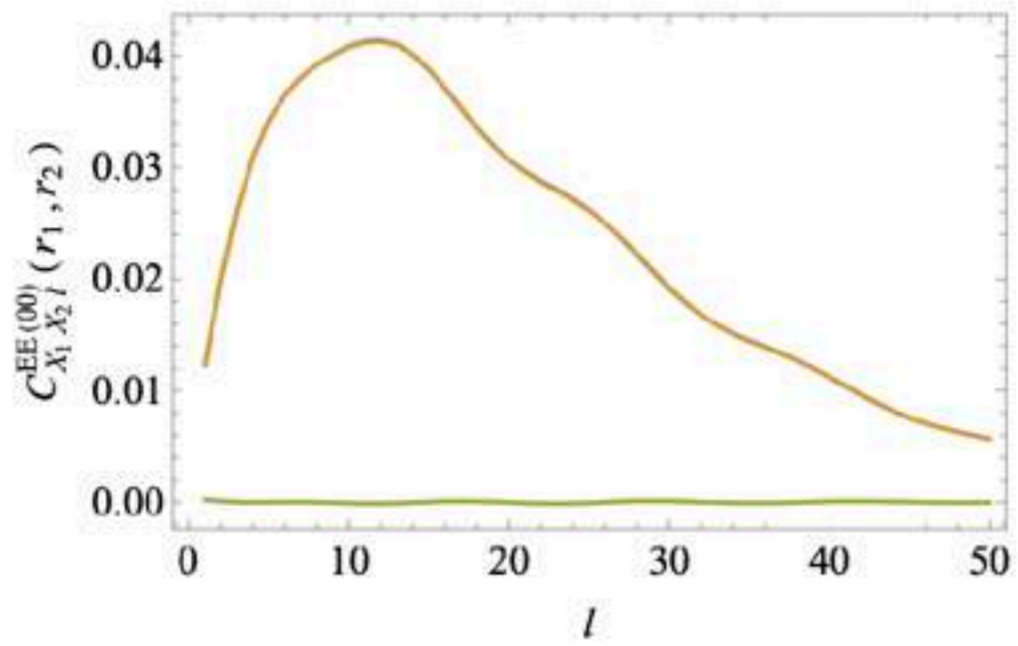


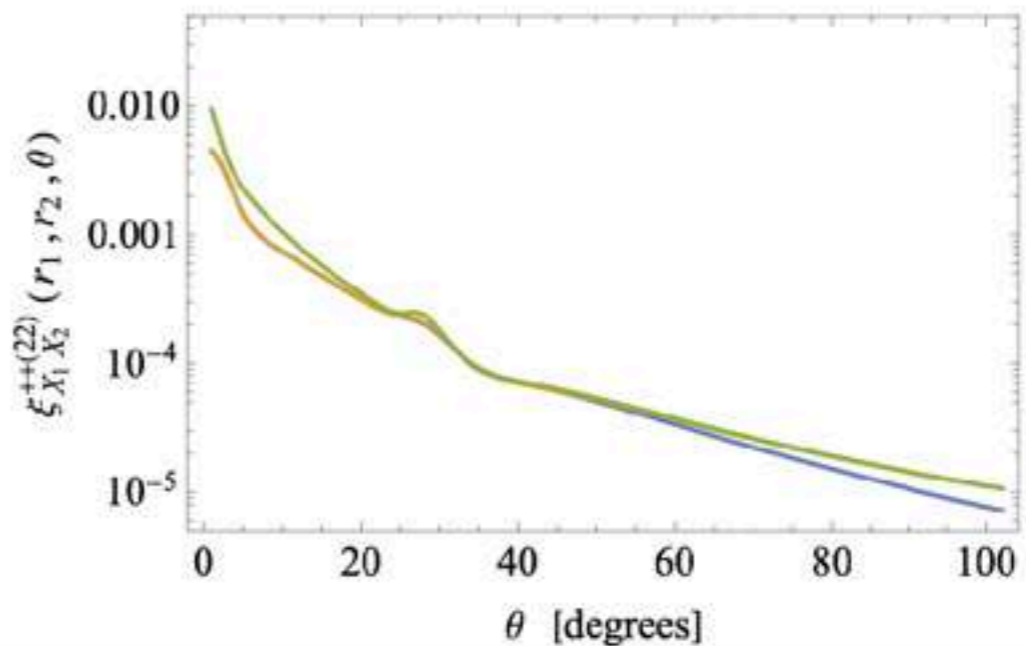
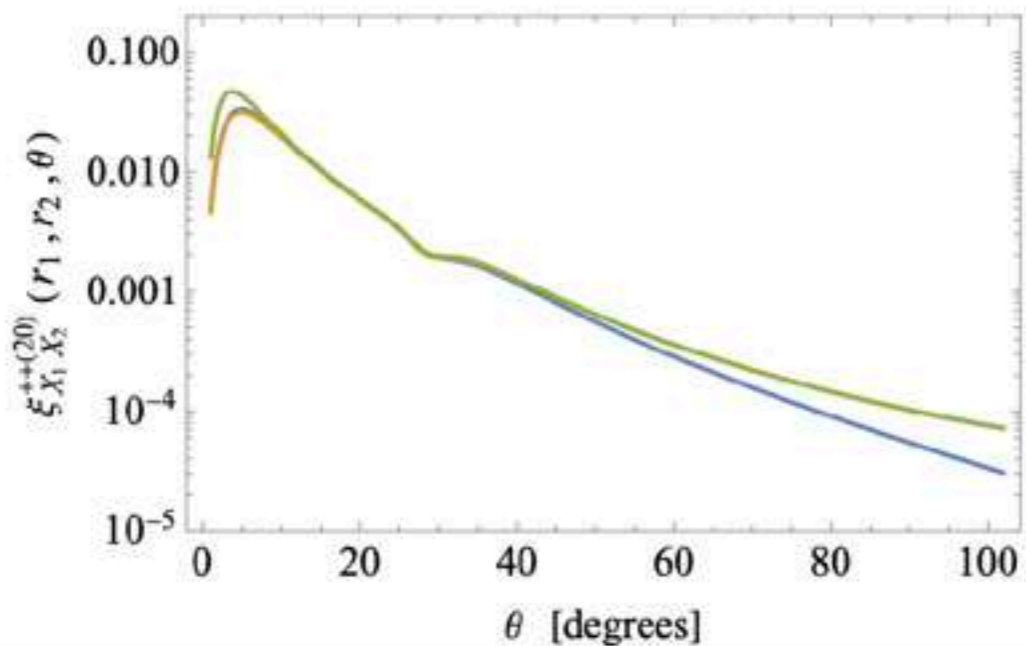
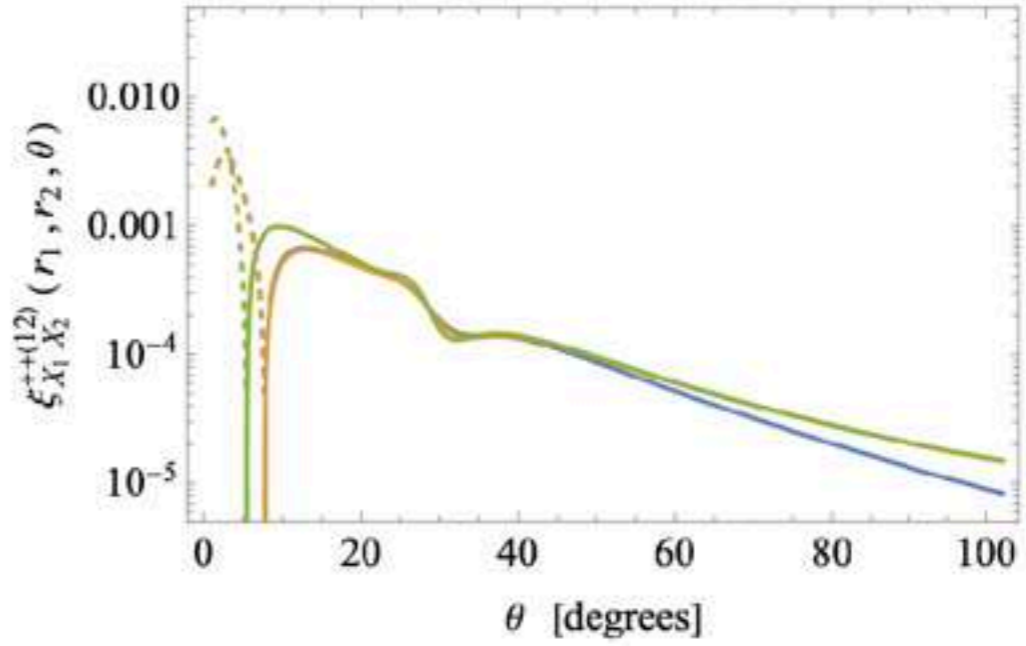
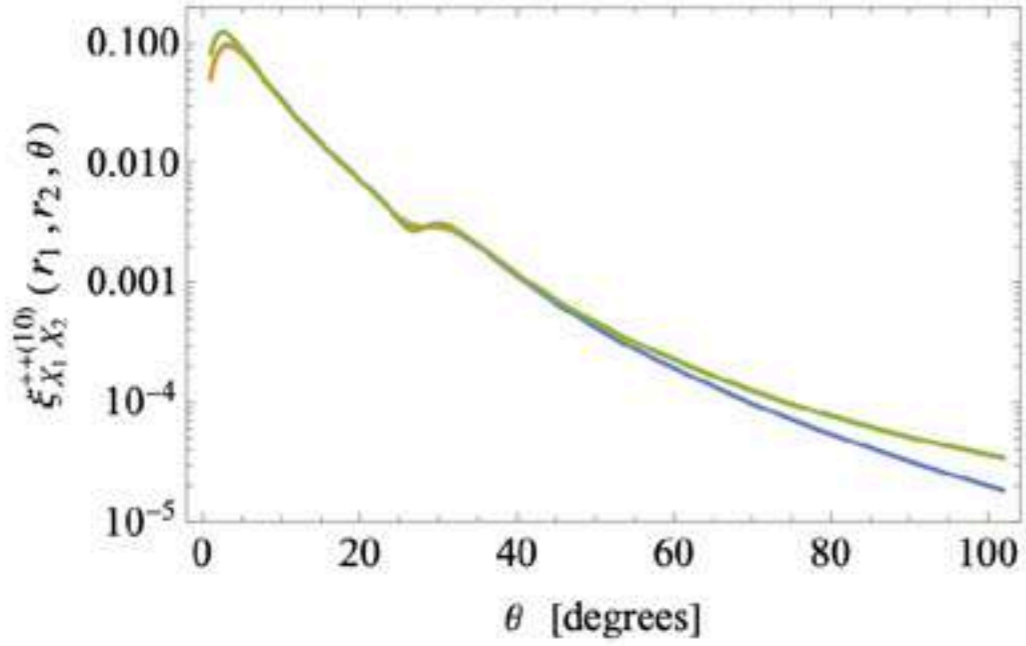
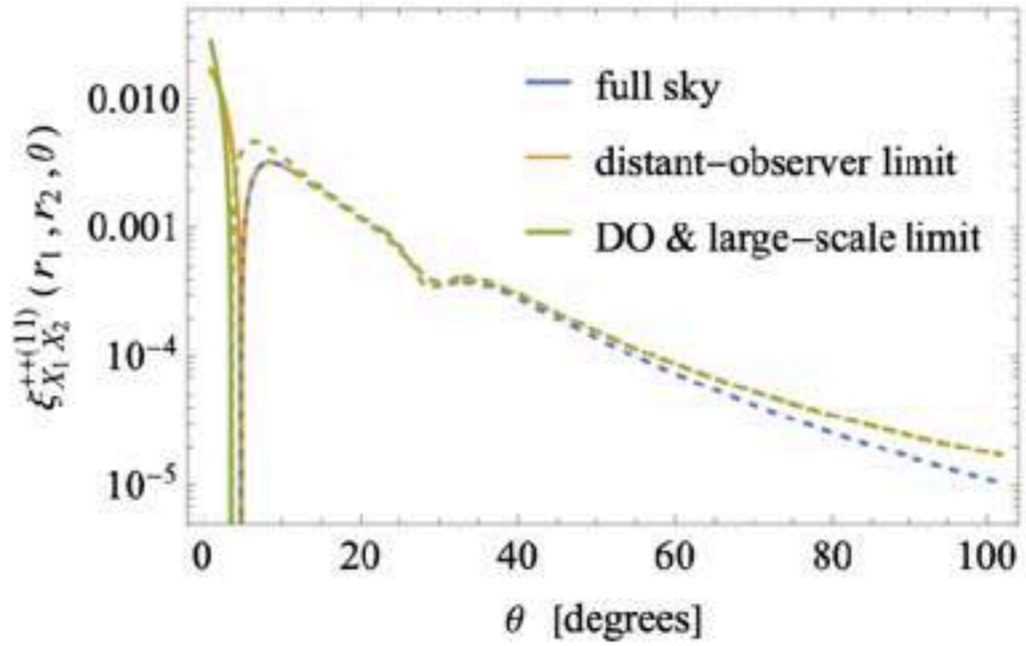
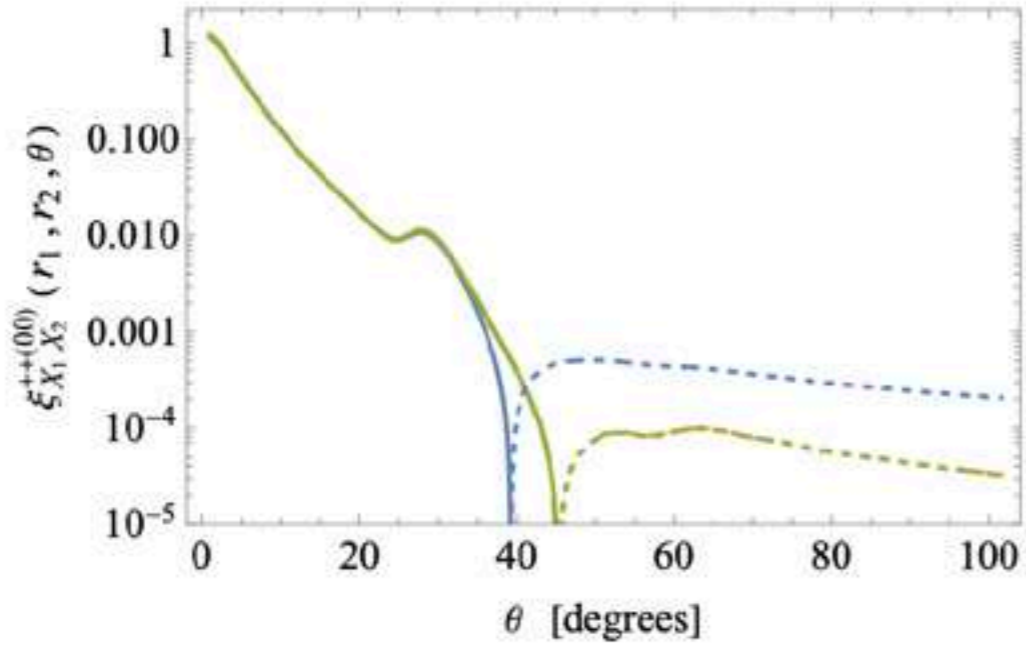
$$\begin{pmatrix} e_\theta(\theta, \phi) \\ e_\phi(\theta, \phi) \\ e_r(\theta, \phi) \end{pmatrix} = \begin{pmatrix} \cos \theta \cos \phi & \cos \theta \sin \phi & -\sin \theta \\ -\sin \phi & \cos \phi & 0 \\ \sin \theta \cos \phi & \sin \theta \sin \phi & \cos \theta \end{pmatrix} \begin{pmatrix} e_1 \\ e_2 \\ e_3 \end{pmatrix}$$

\swarrow
 $S_{ij}(\theta, \phi)$

$$\begin{aligned} \tilde{Y}_{i_1 \dots i_s}^{(\sigma)}(\theta, \phi) &= Y_{i_1 \dots i_s}^{(\sigma)} |_{e_1 \rightarrow e_\theta, e_2 \rightarrow e_\phi, e_3 \rightarrow e_r} \\ &= Y_{j_1 \dots j_s}^{(\sigma)} S_{j_1 i_1}(\theta, \phi) \cdots S_{j_s i_s}(\theta, \phi) \\ &= \sum_{\sigma'} Y_{i_1 \dots i_s}^{(\sigma')} \underline{D_{(s)\sigma}^{\sigma'*}(\phi, \theta, 0)} \end{aligned}$$

Wigner's rotation matrix





Application of the perturbation theory

- Theoretical predictions from perturbation theory
 - In Paper I, systematic methods to derive the invariant spectrum from the “integrated Perturbation Theory” (iPT, Matsubara 2011) are formulated
 - In Paper II, further methods to calculate nonlinear corrections in perturbation theory are developed
 - In Paper III, the iPT is applied to the formulas of projection effects
 - In Paper IV, the formulas are generalized to those in the full-sky, without assuming the flat-sky, distant-observer limit.